

user manual

pco.edge family



pco.

Target Audience: This camera is designed for use by technicians, engineers, and scientists.

In case of any questions or comments, please contact us at PCO.



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The cover photo shows an exemplary PCO camera system.
The lens is sold separately.

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1. INTRODUCTION



Advantages of the pco.edge family

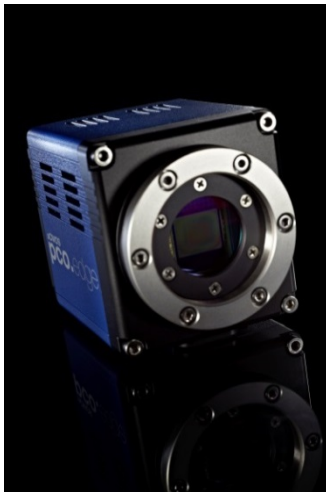
The pco.edge family is a breakthrough in scientific imaging cameras. It has the distinctive ability to simultaneously deliver extremely low noise, high frame rates, wide dynamic range, high quantum efficiency, high resolution and a large field of view - all in one image.

The camera's main features (camera-specific)

- **ultra low noise** 0.8 electrons med (pco.edge (gold) 4.2)
- **high resolution** 5.5 megapixel (pco.edge 5.5)
- **best dynamic range** 36000:1 (pco.edge (gold) 4.2)
- **high-speed** 100 fps @ full resolution (pco.edge 4.2 & 5.5, Camera Link)
- **high quantum efficiency** up to 70% (pco.edge 4.2)
- **deep cooling** down to - 30 °C (pco.edge gold, water cooling)
- **flexibility** user selectable choice of shutter mode
- **free of drift** stabilized Peltier cooling in order to avoid any drift phenomena in image sequences

Areas of Application

- | | |
|---|---|
| • live cell microscopy | • FRAP |
| • single molecule detection | • lucky astronomy / imaging |
| • localization microscopy | • adaptive optics |
| • lightsheet microscopy | • solar astronomy |
| • selective plane illumination microscopy | • fluorescence spectroscopy |
| • SPIM | • bio- & chemiluminescence |
| • structured illumination microscopy | • high content screening |
| • SIM | • photovoltaic inspection |
| • TIRF microscopy / waveguides | • x-ray tomography |
| • spinning disk confocal microscopy | • ophthalmology |
| • genome sequencing (2nd and 3rd gen) | • flow cytometry |
| • FRET | • biochip reading |
| | • machine vision |
| | • spectral (hyperspectral) imaging |
| | • laser induced breakdown-spectroscopy (LIBS) |



Overview – Available camera models

This table shows an overview over all available camera models.

Type	Interface	Shutter	Read Out Frequency	FPS (Max)	Sensor
pco.edge 4.2	USB 3.0	Rolling (RS)	110 MHz	40	mono
pco.edge 4.2	Camera Link	Rolling (RS)	95.3 MHz (slow scan)	30	mono
			272.3 MHz (fast scan)	100	mono
pco.edge gold 4.2	USB 3.0	Rolling (RS)	110 MHz	40	mono
pco.edge 5.5	USB 3.0	Rolling (RS)	86 MHz	30	mono & color
		Global (GS)	under development	-	
pco.edge 5.5	Camera Link	Rolling (RS)	95.3 MHz (slow scan)	30	mono & color
			286 MHz (fast scan)	100	
		Global (GS)	286 MHz (fast scan)	50	
		Global Reset (GR)	95.3 MHz (slow scan)	30	
			286 MHz (fast scan)	90	
pco.edge gold 5.5	USB 3.0	Rolling (RS)	86 MHz	30	mono & color
		Global (GS)	under development	-	

*since the image quality in Global Shutter Mode decreases with slower readout frequency, the slow scan mode is disabled.

2. SAFETY INSTRUCTIONS



Please read the safety instructions completely

Never operate the camera in humid or dusty environments or in places with high amounts of X-ray radiation. **Humidity, dust or X-rays could damage the camera.**



To avoid the risk of water condensation, protect the camera against extreme changes of ambient temperature. **If condensation enters the camera, there is the risk of electric shock.**



To prevent damage to the camera, **the system must be kept stable and protected against strong jolts or vibrations.** The socket at the bottom of the camera is to be used for mounting purposes only.



Electric shock warning – **Never slide any items through slits or holes into the camera** because of the risk of electric shock if the voltage parts inside are touched.



Each time the camera is used, **check the power cable for any damage.**







Never position the cable in a way that it could become a **tripping hazard.**



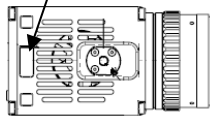
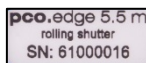
Do not force the lens onto the camera. To protect the lens connector thread from damage, use minimal force when attaching a lens to the camera.



If any of the following conditions apply, immediately switch off the camera, separate it from the power line and contact our customer support:

-  If the power cable or the power plug seems to be worn or damaged.
-  If liquids have penetrated the device.
-  If, after thoroughly reviewing the instruction manual, the device is still not operating properly.
-  If the camera has been dropped or the casing is damaged.

3. SYSTEM COMPONENTS



The camera system includes the following parts.

Camera Head

F-mount optical connection (standard)

For standard F-mount / SLR lenses and adapters.

C-mount ring provided (see appendix **A2**)

For standard C-mount and microscopy connectors.

DC Power Jack (connect to power supply)

Input/Output 4x SMA connectors (2x input - 2x output)

Interface (user selectable) Dual Camera Link full or USB 3.0

LED indicates camera status

Green continuous: camera is booting

Green blinking: camera is ready for operation

Yellow blinking: recording on

Red blinking: error



Serial Number Tag (on the bottom of the camera)

Mounting Thread

1/4-20 UNC mounting thread

Camera Link Grabber Card / USB 3.0 PCI Interface Card

PCI Express x4 Card (Camera Link **full**) or

PCI Express x1 Card (2 x USB 3.0 connections)

A PCI Card with 4 x USB 3.0 connections is also available, contact PCO for further details. A PCIe x4 slot is necessary for this card.

Power Supply

Your system will be equipped with either a 24 V or a 12 V power supply, depending on the model you selected. (connector: Lemo FGG.0B)

Cable

CameraLink Cable (picture) or USB-A/USB-B cable (5m)

Digital Camera Tools (USB storage device content)

- CamWare: software for camera control & image acquisition
- Camera driver & tools
- Software development kit (SDK) & demo programs in C and C++

4. INSTALLATION

You will find all necessary files on the accompanying USB storage device. You may also download the newest versions of our software, camera driver and third party software drivers from our Website (www.pco.de).

Minimum system requirements:

- Clock speed > 2 GHz
- RAM > 4 GB
- Windows 7 or higher
- 1280 x 1024 pixel resolution display
- USB 3.0 or Camera Link

4.1 CAMERA DRIVER

There are two different camera interfaces available:

Camera Link (Frame Grabber)

When operating the camera with **Camera Link Interface**: Please run the appropriate grabber driver installation (provided with the accompanying USB stick) with default settings.

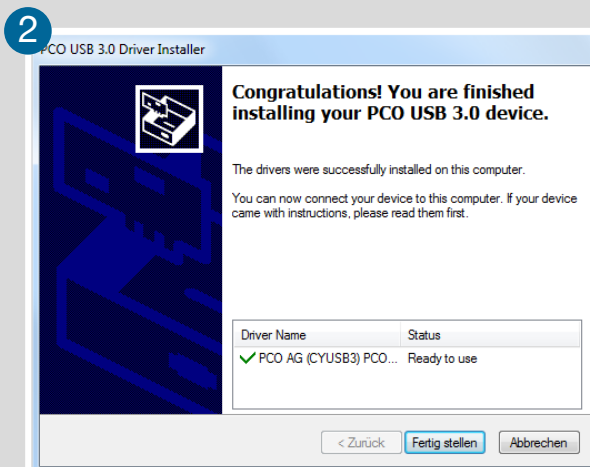
For **detailed installation instructions** please see appendix **A5** (ME4 Grabber Instruction).

USB 3.0

When **USB 3.0** is used as a camera interface, it is recommended to use the enclosed **PCI Interface card**. For **detailed installation instructions** or further hardware recommendations, see **A6**.

Install PCO USB 3.0 Driver

For pco.edge USB 3.0 you always need to install the latest USB Driver version. After these two screens **1** **2** the driver is completely installed.



4.2 CAMWARE

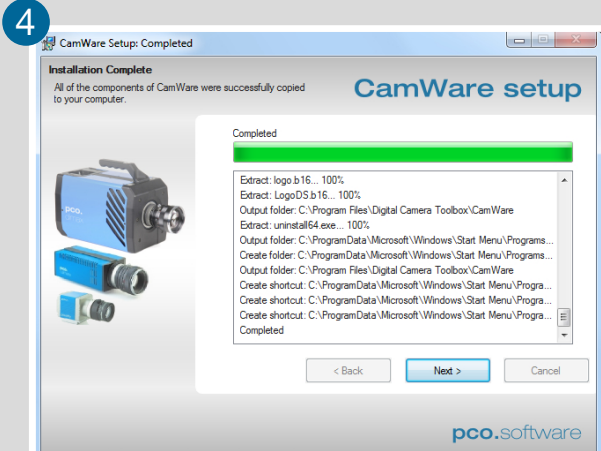
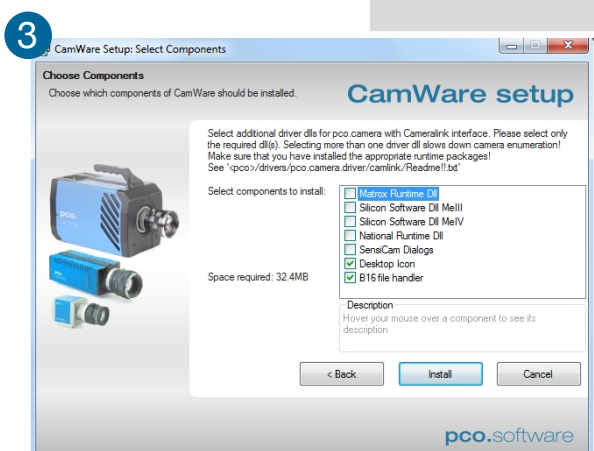
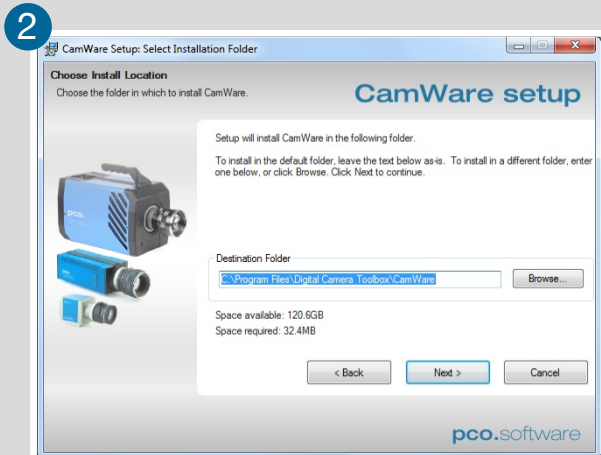
The CamWare Windows application software enables you to control every camera parameter or setting. Images can be displayed on a monitor and may be downloaded and stored. The USB storage device contains the installation files for the software for latest Windows operating systems in 32 & 64 bit.

After a successful installation, you will find the program file **Digital Camera Toolbox** in your program directory and a **CamWare32/64 button** on your desktop. Other helpful tools are also installed in the same directory.

To uninstall the CamWare program, please use the Software feature under Windows' System Control.

Please follow the installation wizard

- 1 Install CamWare as Admin to install to program folder, instead it will be installed only to user folder.
- 2 Then choose install directory.
- 3 Choose components: Select additional drivers for camera Link Interface
- 4 After the next two screens installation is complete.



5. QUICK START

In order to get familiar with your new camera and software it might be helpful, if you first aim at an object that is easy to focus and that can be seen at standard light conditions.

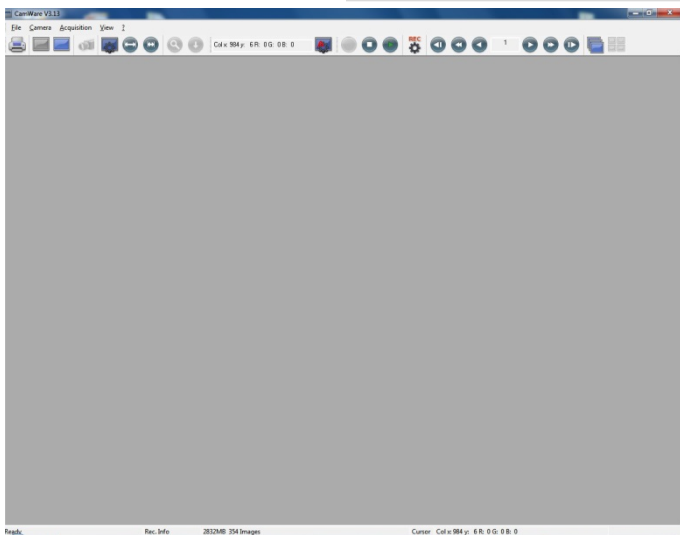
5.1 PREPARATION

- **Computer** is turned on
- **Installation** is finished (see chapter 4)
- **An appropriate lens** is attached (remove cap) or the camera is attached properly to the microscope, spectrograph or other scientific device
- **Camera** is connected to the PC (USB 3.0 or CameraLink)
- **Camera** is connected to the power supply and ready (LED green blinking)

5.2 START



Start **CamWare** and the **graphical user interface** will start up:



NOTE

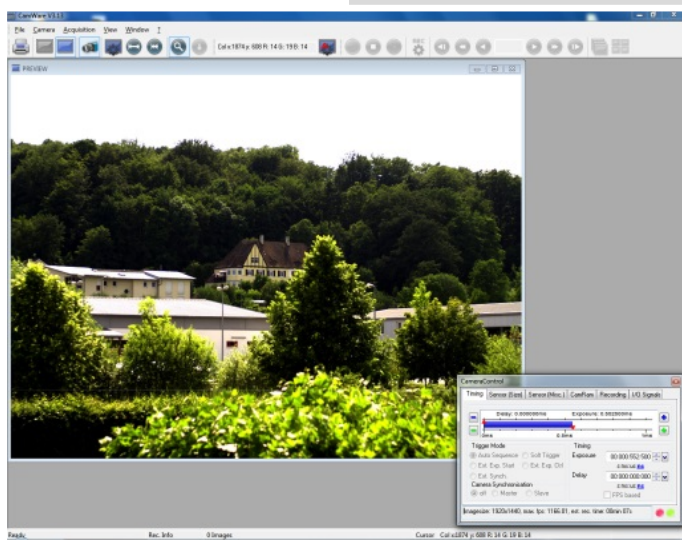
Always install latest CamWare version to get access to the full functionality of your pco camera.

5.3 YOUR FIRST IMAGE

Please follow the instructions:



- 1 **CamWare** must be started
- 2 Open view window (**b/w or color**)
- 3 Start **live preview**
- 4 Apply **auto range peak**
- 5 You may adjust **exposure time**, **aperture** and **focus**
- 6 Now you should clearly see the **object** in the window



If you need to change **exposure** time (e.g. the image is still either too dark or too bright), please go to chapter 6.1.

If you want to record and save images, please see chapter 6 and chapter 7 for detailed information.

(Screenshot shows color camera)

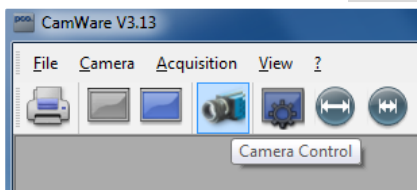
NOTE

Live preview: Useful for fast and easy camera adjustment and focusing. This command disables the Camera Control window if it is opened (except exposure time setting).

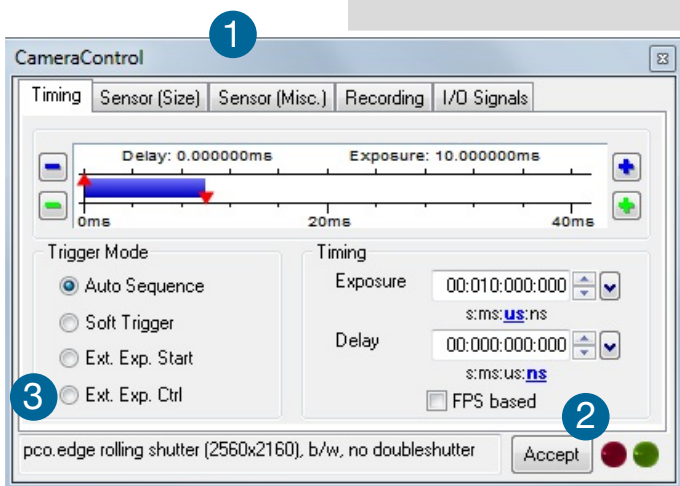
6. CAMERA CONTROL

The **Camera Control** window in CamWare is the main interface for all camera settings. For further CamWare features please see chapter 7.

6.1 THE CAMERA CONTROL WINDOW



The camera control window can be opened by selecting the proper command in the **Camera**-Menu or by the corresponding button in the toolbar.



The camera control dialog always adapts to the camera type connected. For the pco.edge the camera control settings are spread over five **property sheets** ①, which will be explained at the next pages.

Changes to the camera control sheets must be completed by pressing the **Accept button** ②.

In the **information field** ③ you can see some information about the camera. Click into the info field to change the displayed views.

There are three available views of the **information field** ③

pco.edge 5.5 rolling shutter (2560x2160), b/w, no doubleshutter

Camera type

El. Temp.: 33 °C, Sensor Temp.: 5 °C, Power Temp. 34 °C

Actual temperatures

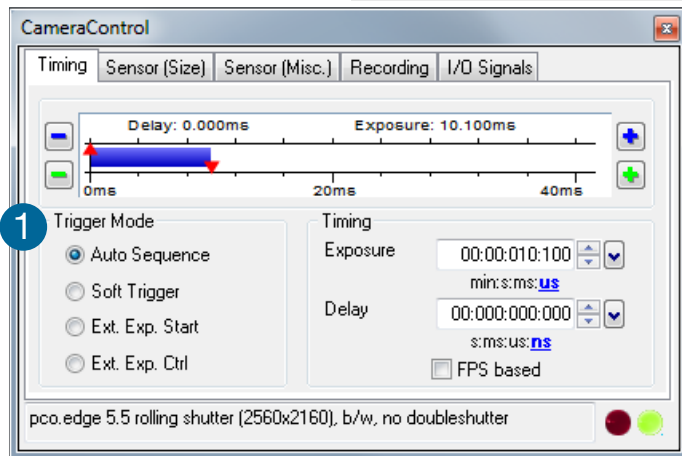
Imagesize: 2560x2160, max. fps: 99.90

Image size and frame rate

NOTE

If the **Accept** button is not pressed, these changes will be ignored and lost. If the changes are within the allowed condition limits of the camera, a message is sent to the computer, the button disappears and the green lamp will be highlighted. The camera control dialog automatically adjusts settings in case they are out of limits.

6.2 THE TIMING TAB



NOTE

If the trigger rate of the external signal is quite near the maximum possible frame rate (difference $< 1/1000$), then it will be random, whether or not a trigger is accepted!

In this context trigger means exposure trigger, i.e. the trigger signal controls the exposure of a single image (light integration time).

Trigger Mode 1

Auto Sequence The camera will optimize the image recording to achieve the best possible frame rate.

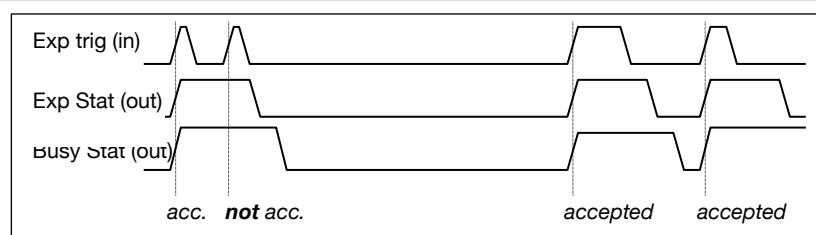
In the auto sequence exposure control mode, the camera determines the fastest possible frame rate depending on the adjusted exposure time and the required readout time.

After a start command is given, the sequential recording is started until a stop command is given.

Soft Trigger Single images can be recorded with this CamWare command. The single image can be acquired by pressing the **Single Trigger** button. This button appears after pressing the **Start Record** button (see 7.2). Other signals cannot influence this operating mode. For test purposes only.

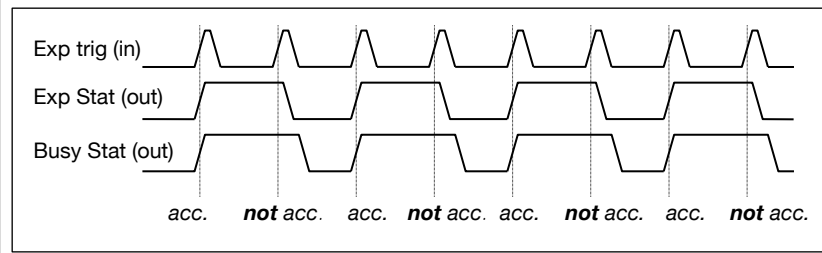
In the **External Exp. Start** exposure control mode, single image recording is started by the falling or rising edge of the voltage signal at the BNC input #1 (see 6.6). The frame rate cannot be set, as the frame rate is defined by the frequency of the external signal. However the predefined exposure time and ROI settings affect the maximum possible frame rate.

The **Busy Status** signal at BNC #3 (BNC explanation see 6.6) will indicate if a new trigger is accepted.



The maximum achievable frame rate in external trigger mode is negligibly less (about 0.1%) than operating the camera in **Auto Sequence** mode.

If the trigger rate of the external signal is higher than the maximum possible frame rate, then every second trigger pulse is ignored. Therefore the actual frame rate drops to half of the external trigger rate. If the trigger rate is increased further, then only every third, every fourth etc. trigger edge will be accepted.



In order to avoid trade-offs at maximum frame rate use either the Busy Status signal or make sure that the external trigger rate follows this condition: External Trigger Rate $\leq f_{\max} / 1.001$.

External Exp. Ctrl An external signal applied at BNC #1 (see 6.6), controls the **start** and the **duration** of the exposure.

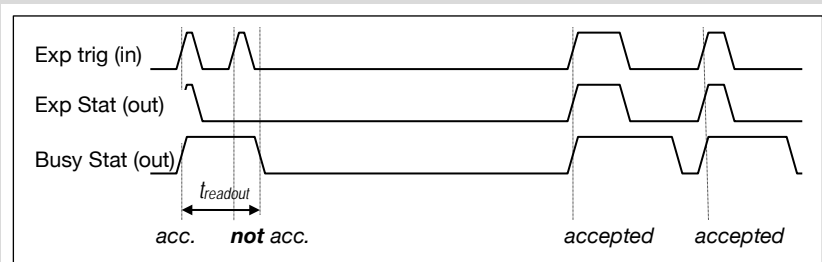
A new exposure is started by the falling or rising edge of the voltage signal at the BNC input. The exposure is finished when the opposite edge is detected. Thus in this mode, the start as well as the length of the exposure time can be controlled.

No further settings can be made, as the image timing is completely controlled by the external trigger signal.

Be aware, that the externally controlled exposure time is limited. The integration will be stopped automatically if the maximum exposure time is achieved.

Camera	Interface	Shutter Mode	Max. exposure time
pco.edge 4.2	Camera Link	Rolling Shutter	10 s
	USB 3.0		20 s
pco.edge gold 4.2	USB 3.0	Rolling Shutter	60 s
pco.edge 5.5	Camera Link	Global Shutter	100 ms
		Rolling Shutter	2 s
		Global Reset	2 s
pco.edge 5.5	USB 3.0	Rolling Shutter	2 s
pco.edge gold 5.5	USB 3.0	Rolling Shutter	10 s

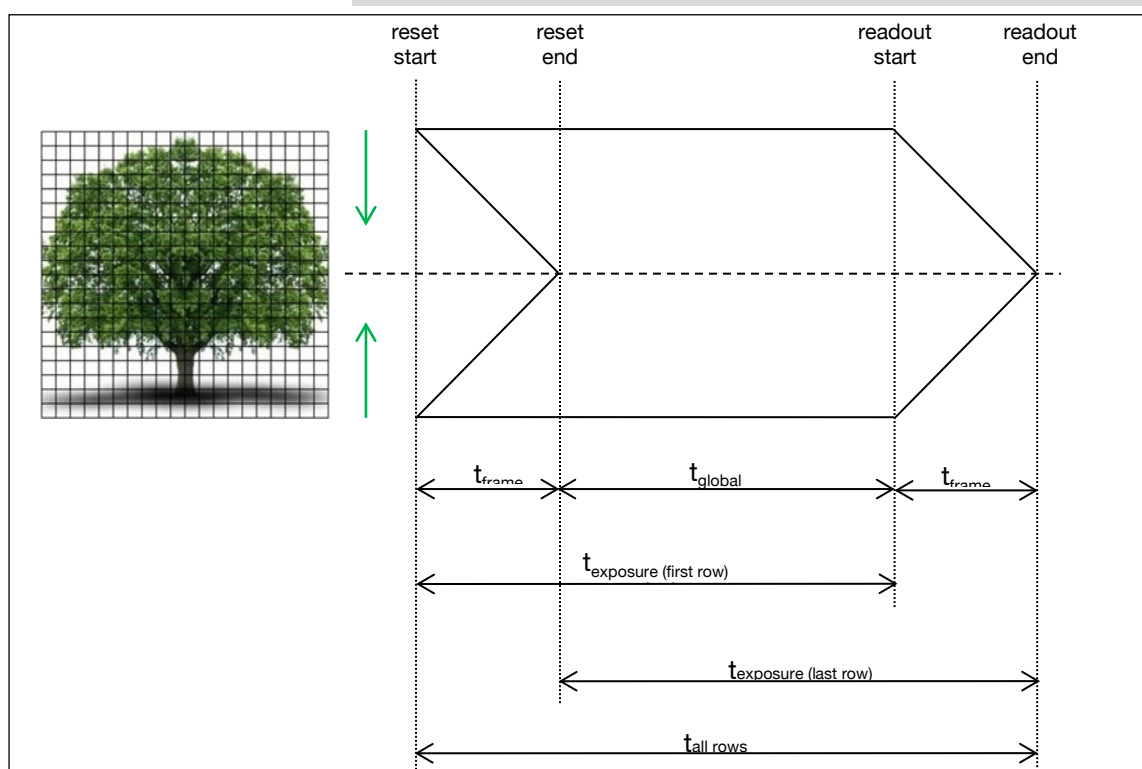
The Busy Status signal at BNC #3 (see 6.6) indicates if a new trigger is accepted.



6.2.1 ROLLING SHUTTER

In **Rolling Shutter** mode the pixel reset and exposure start is carried out row by row. Each row has the same exposure time, but a different start of exposure. The pco.edge image sensor consists of two discrete halves, which are exposed and read out simultaneously, i.e. from the outside to the center. Within one row, the exposure starts simultaneously for all pixels. Available **RS** readout modes see 7.4.

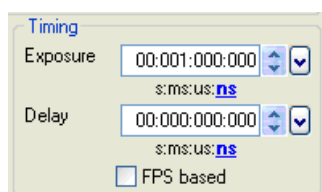
General Timing Diagram



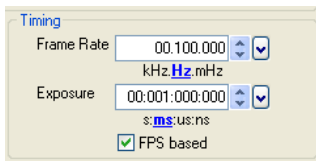
The exposure time of each row starts with the corresponding reset of the row. Then after a predefined time, the exposure is stopped. The light induced accumulated charge carriers of the pixels in a row are recorded into memory in a low noise (readout) mode. This results in the total image appearing in memory corresponding to the row readout.

Timing

The exposure and delay time can be adjusted in steps of 10µs.



Camera (RS only)	Interface	Exposure time	Delay time
pco.edge 4.2	Camera Link & USB 3.0	100 µs ... 10 s	0 µs ... 1 s
pco.edge gold 4.2	USB 3.0	100 µs ... 60 s	0 µs ... 1 s
pco.edge 5.5	Camera Link & USB 3.0	500 µs ... 2 s	0 µs ... 1 s
pco.edge gold 5.5	USB 3.0	500 µs ... 10 s	0 µs ... 1 s



FPS based The camera will optimize the image recording to achieve the selected frame rate with chosen exposure time as close as possible.

- Only for **Auto Sequence** trigger mode
- **FPS based** mode only available with **Camera Link** Interface

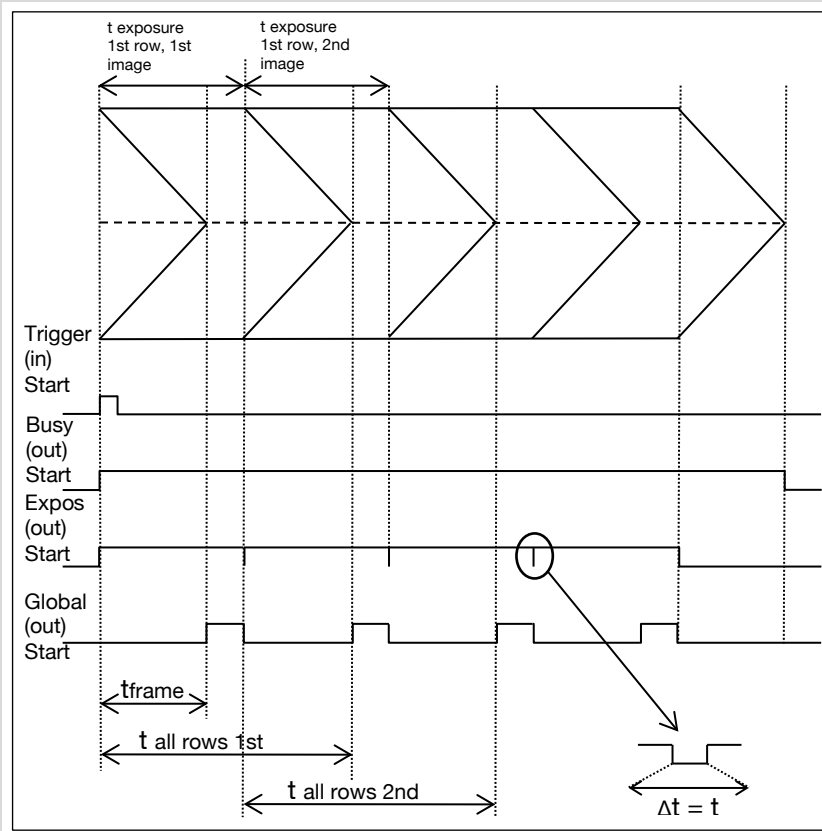
First the frame rate is set. If the time required for readout of the image is longer than $1 / \text{frame rate}$, then the frame rate will be reduced to $1 / t_{\text{readout}}$.

The frame rate can be adjusted in steps of 1 mHz (Rolling Shutter). If the selected exposure time would require a lower frame rate, the exposure time is cut to the maximum possible time at that frame rate.

Camera (RS only)	Interface	Frame rate (FPS Based)	Exposure time
pco.edge 4.2 (@ full resol.)	Camera Link	0.1...35 Hz @ 95.3 MHz	100 μ s...10 s
		0.1...100 Hz @ 272.3 MHz	
pco.edge 5.5 (@ full resol.)	Camera Link	0.5...33.3 Hz @ 95.3 MHz	500 μ s...2 s

Exposure time > Sensor frame readout time (Auto Sequence)

In case the required exposure is longer than the frame readout time, the image sensor is completely exposed to light for some time (t_{global}). In case of a triggered flash illumination, this would be the best moment to illuminate the image sensor.



The hardware signal for the time t_{global} is available on connector #4 (Global out see 6.6). Setting can only be made through SDK (not available in CamWare).

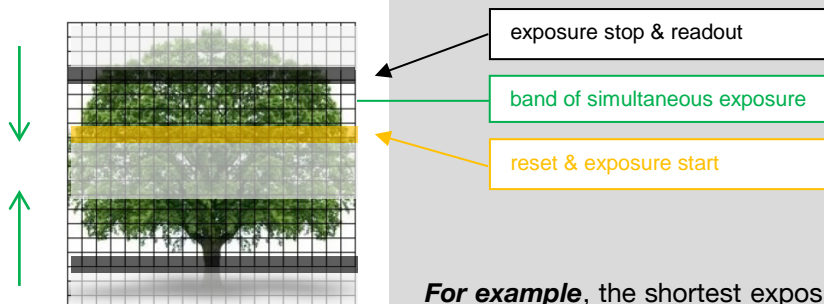
Obviously, if during exposure and readout, parts of the viewed image are moving horizontally, this would result in image distortion. This is why the global shutter mode may be a prerequisite for some applications.

However, most dynamic events can be captured in 1 ms, which is a common integration time with SLR cameras set at 1/1000 exposure. The time shift from one row to another is only about 10 μs (fast scan). The resulting maximum readout time of 10 ms (@ full resolution) seems to be sufficient for a broad spectrum of dynamic events.

The 10 ms is also faster than the image shift process of most frame transfer **emCCD** image sensors previously used for low light applications. If this does not influence the image recording and processing, then rolling shutter mode will not affect it either.

Exposure time < Sensor frame readout time (Auto Sequence)

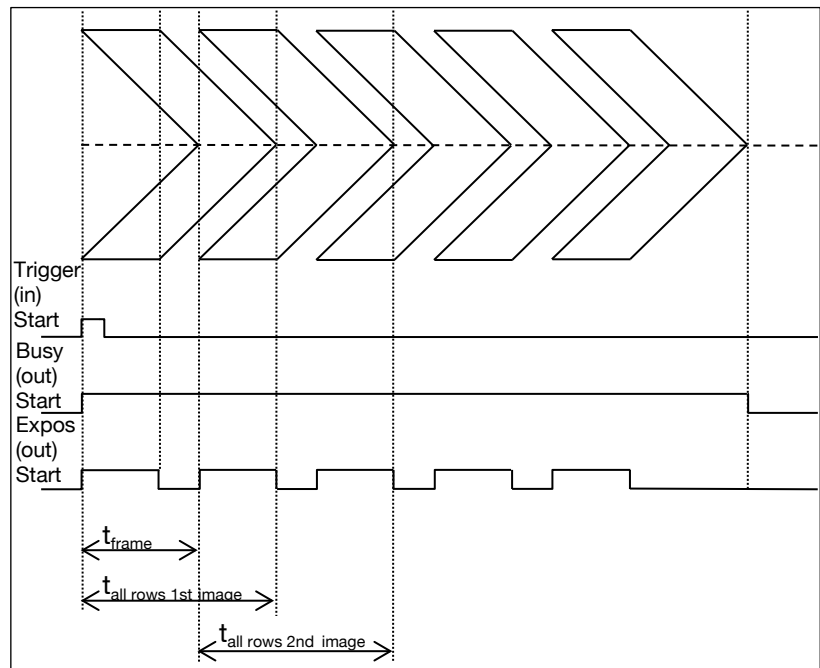
In case the required exposure time is shorter than the frame readout time, the image is composed of two exposure bands moving from the outside to the center of the sensor.



For example, the shortest exposure time in RS (5.5) is 500 μs or 100 μs (4.2). The band of simultaneous exposure is in this case (smallest possible height) at full resolution:

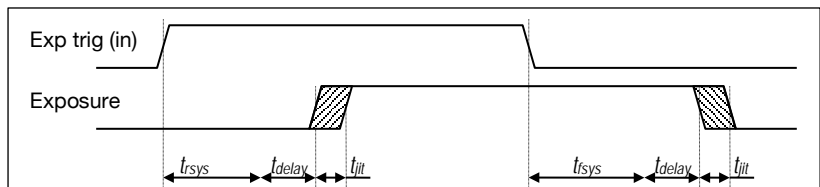
Camera (RS only)	Inter face	MHz	Min. Exposure time	Time per row	Min. number of simult. rows
pco.edge 4.2/ gold 4.2	USB 3.0	110	100 μs	24.10 μs	4
pco.edge 4.2	Camera Link	95.3	100 μs	27.60 μs	3
		272.3	100 μs	9.65 μs	10
pco.edge 5.5/ gold 5.5	USB 3.0	86	500 μs	30.50 μs	16
pco.edge 5.5	Camera Link	95.3	500 μs	27.52 μs	18
		286	500 μs	9.17 μs	54

Previous comments on image distortion (also known as Rolling Shutter Effect) apply here as well.



Details for External Exp. Start and External Exp. Ctrl

The detailed timing for external trigger includes system delay times, an adjustable additional delay time, and the jitter.



NOTE

The jitter t_{jit} can be a maximum of one row time.

Camera (RS only)	Interface	Internal system clock	t_{sys}	t_{jit} (jitter)	t_{delay} (delay)
pco.edge 4.2	Camera Link	72 MHz	70 ns	0 ... 27.60 μs (slow scan)	0 ... 1 s
				0 ... 9.65 μs (fast scan)	0 ... 1 s
pco.edge 4.2 / gold 4.2	USB 3.0	100 MHz	50 ns	0 ... 24.10 μs	0 ... 1 s
pco.edge 5.5 / gold 5.5	USB 3.0	100 MHz	50 ns	0 ... 30.50 μs	0 ... 1 s
pco.edge 5.5	Camera Link	72 MHz	70 ns	0 ... 27.52 μs (slow scan)	0 ... 1 s
				0 ... 9.17 μs (fast scan)	0 ... 1 s

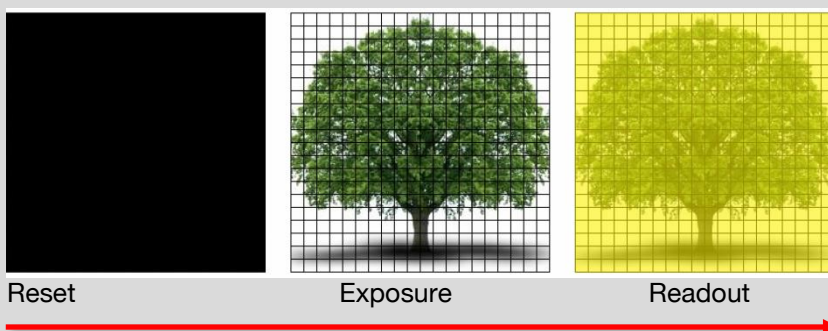
For optimized synchronization (minimized jitter time) use the falling edge of the line signal at the status output (see SDK description).

6.2.2 GLOBAL SHUTTER

NOTE

Global Shutter is only available for pco.edge 5.5 Camera Link and under development for pco.edge gold 5.5 and 5.5 USB.

First, all pixels are globally reset and these reset values are shifted into so-called diffusion nodes. From there, they are non-destructively read out into memory as reset dark images. The exposure starts after transfer of the reset dark image to the diffusion nodes, where they are stored on the chip. The exposure is stopped by global charge transfer to the diffusion nodes. Then, the exposure image is read out to the memory, where the former reset dark image is subtracted to perform an external correlated double sampling, which reduces the noise. Since two images have to be read out to receive one resulting image, the sCMOS image sensor's **Global Shutter** mode has only half of the frame rate of the **Rolling Shutter** mode.



Timing

The exposure and delay time can be adjusted in steps of 10µs.

Camera (GS only)	Exposure time	Delay time
pco.edge 5.5	10 µs .. 100 ms	0 µs ... 1 s

FPS based

The camera will optimize the image recording to achieve the selected frame rate with chosen exposure time as close as possible.

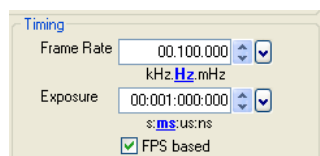
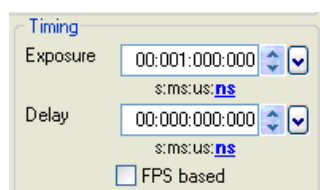
- Only for **Auto Sequence** trigger mode
- **and** only available with Camera Link Interface

First the frame rate is set. If the time required for readout of the image is longer than $1 / \text{frame rate}$, then the frame rate will be reduced to $1 / t_{\text{readout}}$.

The frame rate can be adjusted in steps of 1 mHz (Global Shutter).

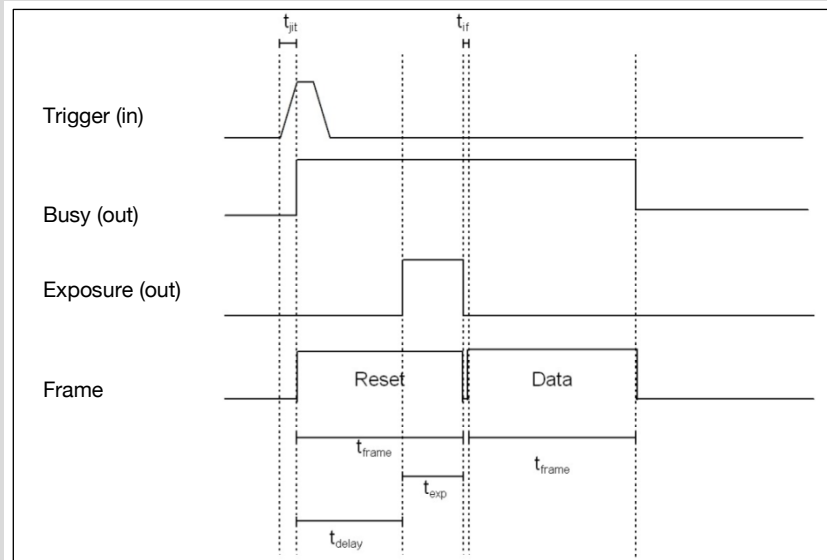
If the selected exposure time would require a lower frame rate, the exposure time is cut to the maximum possible time at that frame rate.

Camera (GS only)	Interface	Frame rate (FPS Based)	Exposure time
pco.edge 5.5	Camera Link	10 ... 50 Hz @ 286 MHz	10 µs ... 100 ms



External Exposure Start

(Auto Sequence respectively)



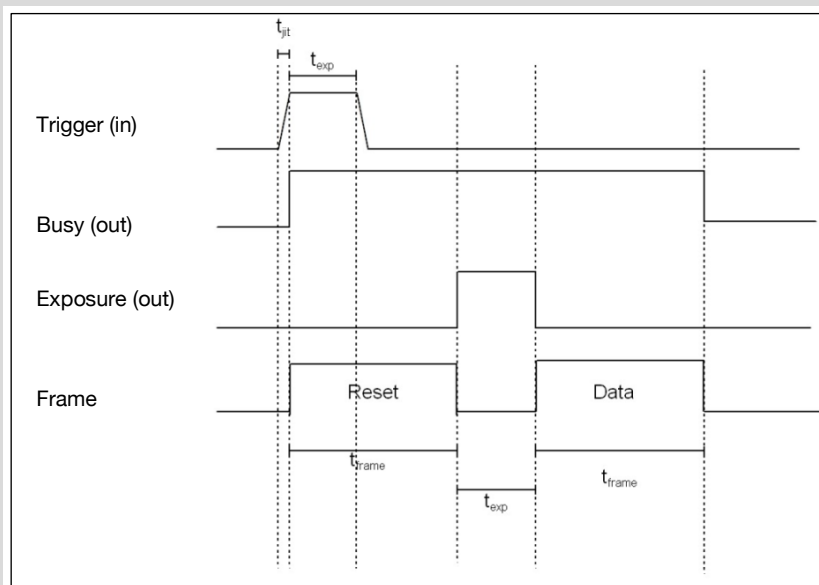
	Number of lines	286 MHz (fast scan)
t_{jit}	1	0 ... 9.17 μ s
t_{frame}	ROI (y)	10.00 ms (max)
t_{exp}	programmable	10 μ s ... 100 ms
t_{delay} (system)	$(t_{frame} - t_{exp})$	
t_{if}	1	9.17 μ s

The listed parameters can be output via SDK function "Get Image Timing" dependent on the selected ROI.

NOTE

if $t_{exp} < t_{frame}$ system delay (t_{delay}) is added before exposure starts.

External Exposure Control



	Number of lines	286 MHz (fast scan)
t_{jit}	1	0 ... 9.17 μ s
t_{frame}	ROI (y)	10.00 ms (max)
t_{exp}	counted	

In **External Exposure Control** trigger mode the external signal controls start of image acquisition and duration of the exposure. First, all pixels are globally reset and these reset values are shifted into so-called diffusion nodes. From there, they are non-destructively read out into memory as reset dark images.

In this mode, the exposure starts always after the readout of the dark image is completed. The length of the exposure has been detected by the sensor from the trigger input. The exposure is stopped by global charge transfer to the diffusion nodes after the respective time. Then, the exposure image is read out to the memory, where the former reset dark image is subtracted to perform an external correlated double sampling, which reduces the noise.

Since two images have to be read out to receive one resulting image and the exposure cannot start during readout time of the dark image, this specific **Global Shutter** mode provides less than half of the frame rate of the **Rolling Shutter** mode.

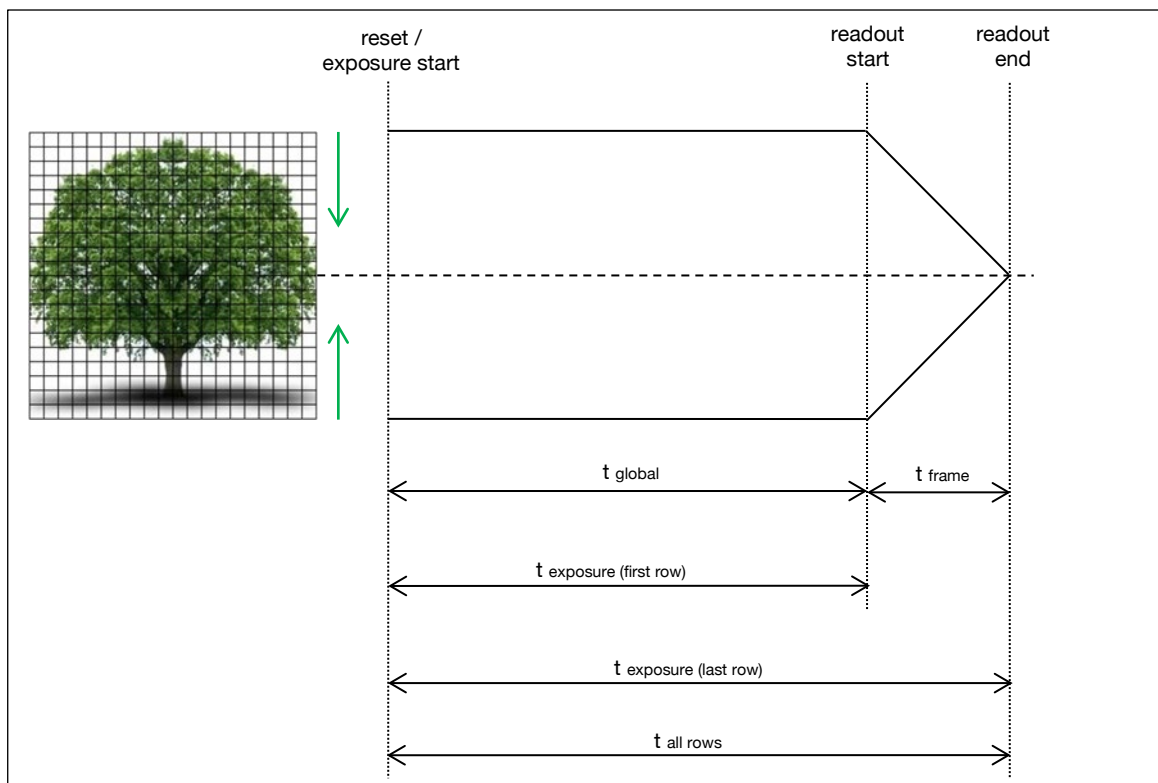
6.2.3 GLOBAL RESET

NOTE

Global Reset is only available for pco.edge 5.5 Camera Link and under development for pco.edge USB 3.0 versions.

All pixels are globally reset, and the exposure starts for all rows at the same time. The exposure stop is carried out row by row; therefore the duration of the exposure is not the same for all pixels. The rolling readout improves the image quality, but due to the difference in exposure time, a flash illumination is recommended. The readout (exposure stop) is done from the outside to the center.

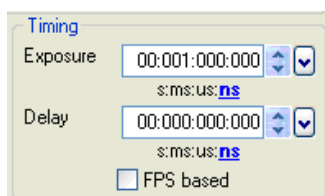
General Timing Diagram



The exposure time of all rows starts simultaneously. The exposure time of the first row stops after the predefined time, the following rows are read out from the outside to the center row by row. Please note that this leads to a different duration of exposure time for all rows.

Timing

The exposure and delay time can be adjusted in steps of 10 μs .



Camera (GR only)	Exposure time	Delay time
pco.edge 5.5	10 μs – 2 s	0 μs ... 1 s

Timing

Frame Rate
 kHz Hz mHz

Exposure
 s:ms:us:ns

☒ FPS based

FPS based

The camera will optimize the image recording to achieve the selected frame rate with chosen exposure time as close as possible.

- Only for **Auto Sequence trigger** mode
- **and** only available with Camera Link Interface

First the frame rate is set. If the time required for readout of the image is longer than $1 / \text{frame rate}$, then the frame rate will be reduced to $1 / t_{\text{readout}}$.

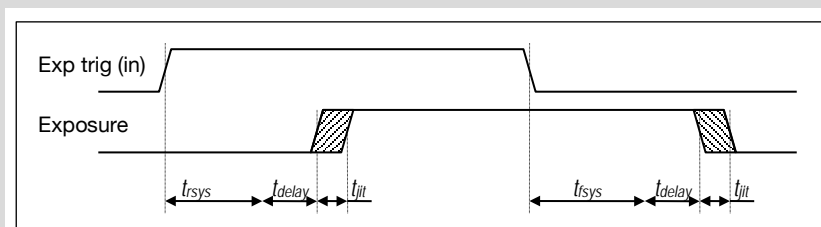
The frame rate can be adjusted in steps of 1 mHz (Global Reset).

If the selected exposure time would require a lower frame rate, the exposure time is cut to the maximum possible time at that frame rate.

Camera (GR only)	Interface	Frame rate (FPS Based)	Exposure time
pco.edge 5.5	Camera Link	1 ... 33.3 Hz @ 95.3 MHz	10µs ... 2s
		1 ... 100 Hz @ 286 MHz	

Details for External Exp. Start and External Exp. Ctrl

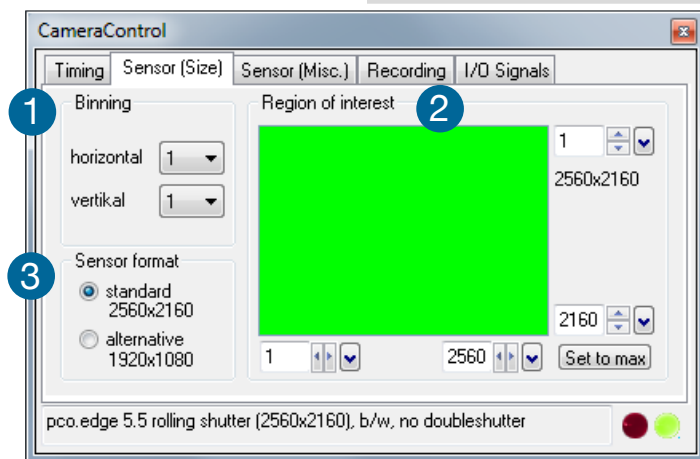
The detailed timing for external trigger includes system delay times, an adjustable additional delay time and the jitter.



Camera (GR only)	Interface	t_{sys}	t_{jit} (jitter)	t_{delay} (delay)
pco.edge 5.5	Camera Link	70 ns	0 ... 27.52 µs (slow scan)	0 ... 1s
			0 ... 9.17 µs (fast scan)	0 ... 1s

For optimized synchronization (minimized jitter time) use the falling edge of the line signal at the status output (see SDK description).

6.3 THE SENSOR (SIZE) TAB



NOTE

Software based ROI (Soft-ROI) is enabled within CamWare by default. Due to this functionality, the resolution of pco.edge cameras with Camera Link interface can be adjusted in steps of 1 – 4 pixels. Since the readout architecture of these cameras is not able to address single pixels, this downsizing is done by software. If you work with Device Adapters (µManager, Labview etc.) or with our SDK, the Soft-ROI is disabled by default. For further information, please see the SDK description.

Binning 1

Binning combines neighboring pixels (in either the horizontal or vertical direction) to form super pixels. It increases the signal to noise ratio (SNR), reduces the readout noise of the resulting pixels and decreases the spatial resolution of the total image, which is recorded.

For further information see **A7**.

Available Binning Modes:

H1xV1, H1xV2, H1xV4, H2xV1, H2xV2, H2xV4, H4xV1, H4xV2, H4xV4

Region of Interest 2

The ROI (Region of Interest) selects only a part of the sensor to be read out.

Vertical ROI: In order to speed up the frame rate and to reduce the amount of image data, the selected ROI needs to be placed symmetrical to the horizontal center line.

Horizontal ROI: In order to reduce the amount of image data a horizontal ROI can be set. Please be aware, that changes in horizontal direction will not increase the frame rate. The decreased image size you see within CamWare is a combination of reduced sensor resolution and software downsizing (Soft-ROI).

Examples of achievable frame rates at a specific ROI can be found in the datasheets of the cameras.

Camera	Interface	ROI, horizontal increments	ROI, vertical increments	Min. ROI	Vert. symm. ROI
pco.edge 4.2	Camera Link	1	1	40x8	no
pco.edge 4.2 / gold 4.2	USB 3.0	4	1	64x16	no
pco.edge 5.5	Camera Link	4	1	160x8	no
pco.edge 5.5 / gold 5.5	USB 3.0	4	1	64x16	no

Controlling the Soft-ROI Option (only Camera Link version)

Start **regedit** and **HKey-Current-User/Software/PCO/Camware** create a DWORD value with the name **DisableSoftROI**. Set this value to 1 in order to disable Soft-ROI. Remove or set this value to 0 in order to enable Soft-ROI by default. Keep in mind that unsymmetrical ROI decreases FPS. Table shows values for Soft-ROI disabled.

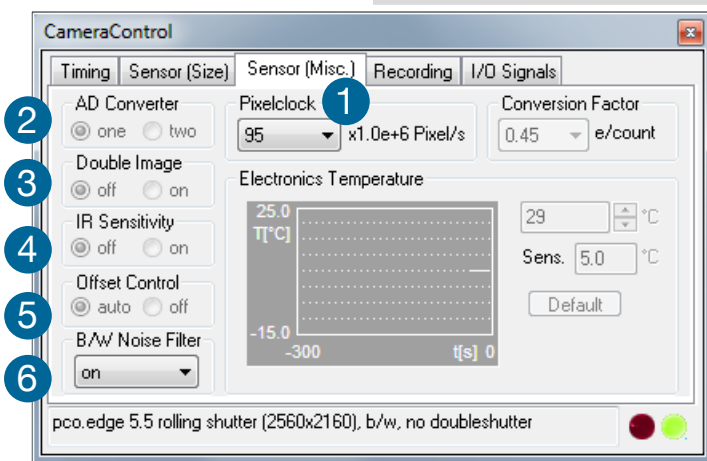
pco.edge 4.2	Camera Link	20	1	40x8	yes
pco.edge 5.5	Camera Link	160	1	160x16	yes

Sensor Format ③

Camera	Interface	Preselected sensor format
pco.edge 4.2	Camera Link	2048 x 2048
pco.edge 4.2 / gold 4.2	USB 3.0	2048 x 2048
pco.edge 5.5	Camera Link	2560 x 2160 1920 x 1080
pco.edge 5.5 / gold 5.5	USB 3.0	2560 x 2160

CamWare will show the actual frame rate, corresponding to the selected image size, in the information box. Imagesize: 2560x2160, max. fps: 33.64

6.4 THE SENSOR (MISC.) TAB



Pixelclock ①

The pixel clock sets the clock frequency and therefore the image sensor readout speed. (See overview table on page 5 (PCO.EDGE FAMILY) for available readout frequencies.)

A/D Converter ②

(not available for pco.edge)

Double Image ③

This feature is widely used for particle image velocimetry (PIV) measurements, but not available for the standard pco.edge cameras.

IR Sensitivity ④

Feature is not applicable for pco.edge.

Offset Control ⑤

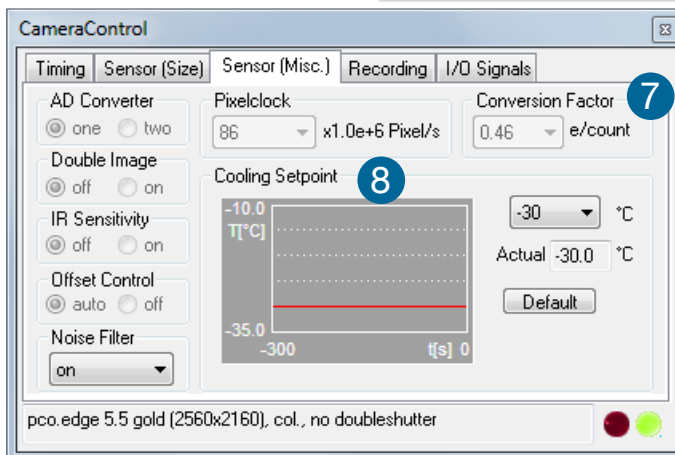
Offset control is done automatically for optimal results. User control is disabled.

B/W Noise Filter ⑥

In addition to the integrated static defect pixel list processing a dynamic noise filter can be activated here in order to remove so-called **blinkers** and **high noise pixels**. If you encounter unexpected aliasing effects, turn this filter off.

Conversion Factor 7

The conversion factor defines how many charge carriers (electrons), which have been generated by light in the image sensor in each pixel, are necessary to generate one count (one intensity level) in the digital image. Therefore, the conversion factor describes the gain that is applied to the signal before it is converted into a digital value. The conversion is optimized for the pco.edge @ 0.46 e/count.



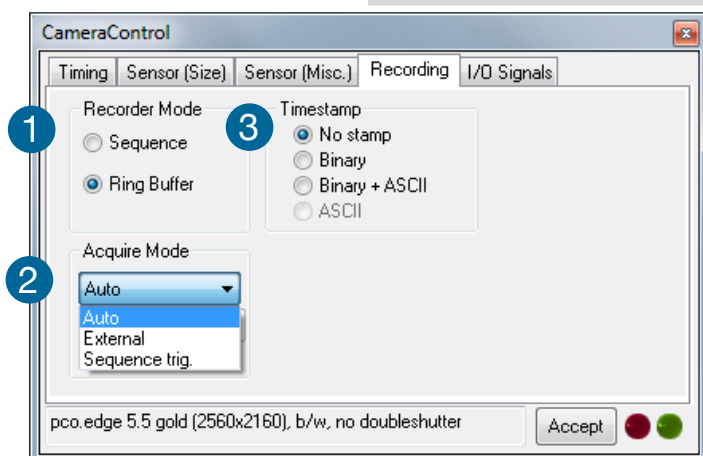
Cooling Setpoint 8

If a **pco.edge gold camera** is connected, a drop-down menu with selectable sensor temperatures will appear.

Display of sensor temperature: A **peltier cooling unit** is used to keep the sensor's dark current to an acceptable minimum and in order to allow for a continuous operation free of any drift phenomena in image sequences. Either an internal fan or an external water cooling system assures proper heat transfer from the peltier element to regulate the temperature of the cameras.

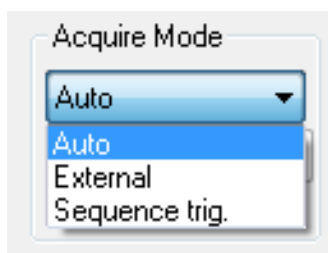
Camera	Interface	Sensor temperature
pco.edge 4.2/5.5	Camera Link	5 °C
pco.edge 4.2/5.5	USB 3.0	0 °C
pco.edge gold 4.2 pco.edge gold 5.5	USB 3.0	- 15 °C - 30 °C (water cooling only)

6.5 THE RECORDING TAB



Recorder Mode 1

CamWare will use free RAM space on your computer. The recorded images will be temporally saved as 16bit multi TIFF. In **Sequence** mode the recording stops when RAM space is full. In **Ring Buffer** mode the camera will stop only by a stop command, hence overwriting previous images. For longer recording periods an appropriate RAID system is necessary, see also the **Direct Record to File** option on p. 36.

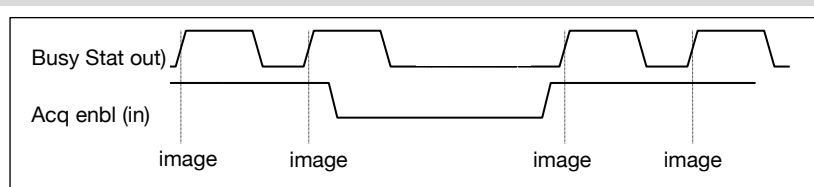


Acquire Mode 2

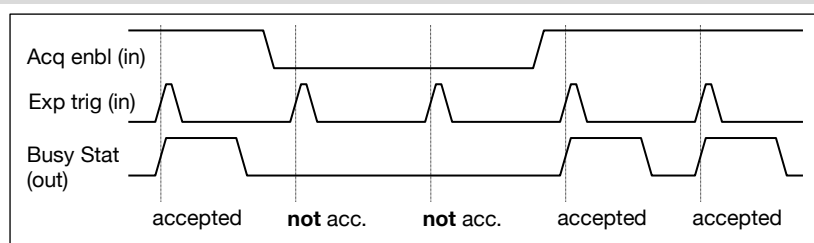
The acquire mode gives you the ability to enable or disable the recording by an external signal. If set to **Auto** all images are accepted and all images taken are saved. A signal at the **acq enbl input** (see chapter 6.6) is ignored for this function.

If set to **External**, the camera will only record images, if the external signal enables recording.

This sensor timing scheme is paused by the signal at the **acq enbl** input. The **acq enbl** input is sampled at the beginning of the image generation, which can be seen at the rising edge of the busy stat output. If the **acq enbl** input is high (low, when inverted) when an image is acquired, it causes an idle state until the **acq enbl** input is low (high, when inverted).

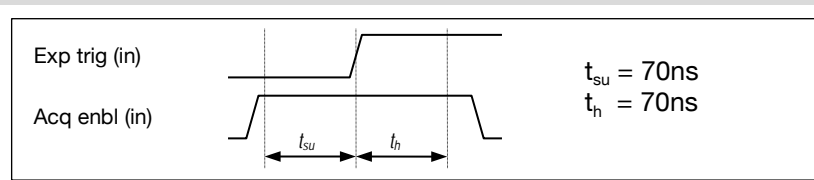


In trigger mode **External Exp. Start**, the **acq enbl** input works like a gate for the trigger signal. A trigger edge (rising, falling when **exp trig** is inverted) is accepted only when the **acq enbl** signal is high (low, when inverted).

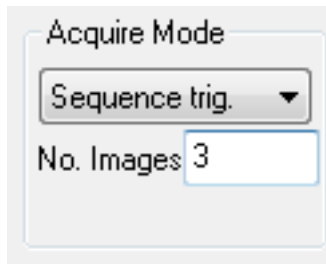


In trigger mode **External Exp. Ctrl**, the **acq enbl** input works very similar to the mode **External Exp. Start**. However, the **acq enbl** input is ignored for the edge which is closing the exposure time (started exposure will be finished accordingly).

When using **acq enbl** in external trigger modes, the following timing specification should be met:



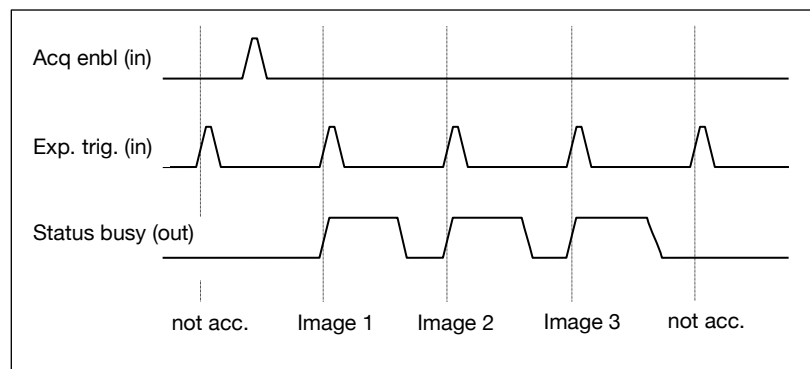
If the **acq enbl** signal changes within the window of t_{su} (set up) to t_h (hold), the behavior is random. The trigger may be accepted or ignored.



Sequence Trigger

Once, a falling or rising edge at the **acquire enable** trigger input (see chapter 6.6) is recognized, an internal image counter starts to run. It will count all acquired images and will stop the recording when the predefined number of images is reached.

Example timing diagram: Trigger mode = external exposure start;
Acquire mode = sequence trigger; Image counter = 3



Timestamp ③

A time stamp can be placed into the upper left corner of the image. It can be either displayed as binary value or as binary and ASCII value.

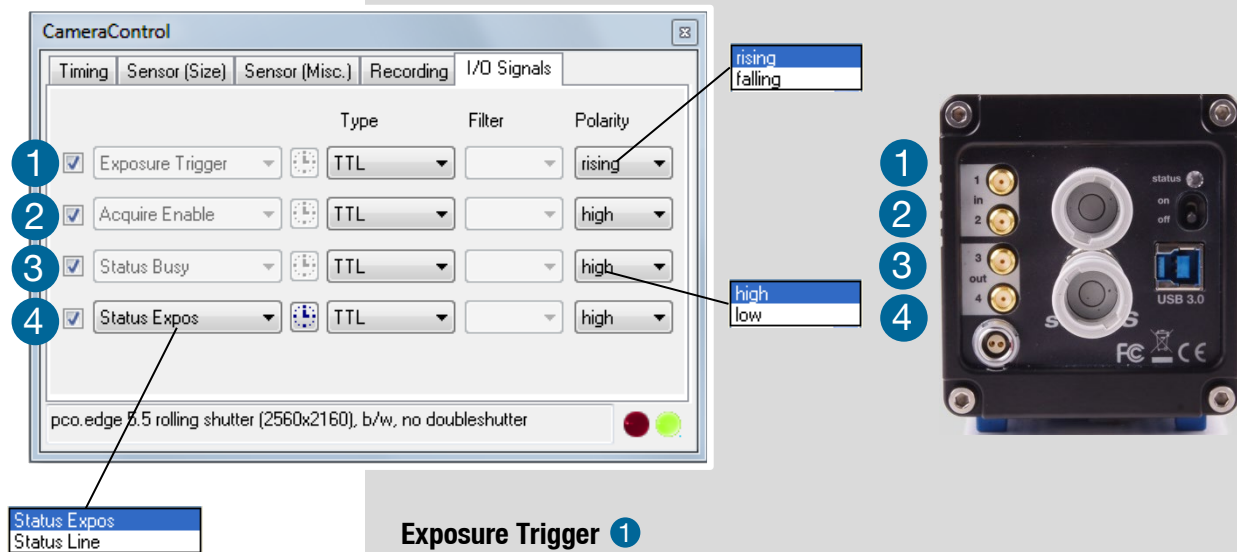
The time resolution is 1 μ s. In binary mode the first 16 pixels ① will be filled with the time stamp information (binary code). The numbers are coded in BCD with one byte per pixel, which means that every pixel can hold 2 digits.

For further information please refer to the SDK. In binary and ASCII mode text will be placed into the image replacing the content of the image (271x 8 pixels). Time step shows the **end** of exposure time.

Three different **information** is stamped onto the image: number of the image ②, date ③ and time ④.



6.6 THE I/O SIGNALS TAB



Exposure Trigger ①

If checked, a signal for External Exp. Start or External Exp. Ctrl trigger mode (see chapter 6.2) is accepted at the **exp trig** BNC input #1.

Acquire Enable ②

If checked, a signal for Acquire Mode or Sequence Trigger Mode (see chapter 6.5.) is accepted at the **acq enbl** BNC input #2.

Status Busy ③

If checked, a signal indicating busy status is given at the status busy output. Once an acceptable trigger edge is received, **busy** will go on status **high**. As soon as busy goes **low** again, a new trigger edge is accepted.

Status Expos ④

If checked, a signal indicating exposure status is given at the status output. Status Expos indicates the actual exposure window for one frame.

Status Line ④

If checked, a signal indicating line status is given at the status output. Use the falling line edge for optimized synchronization (minimized jitter time; see page 18).

Filter (electrical interference filters)

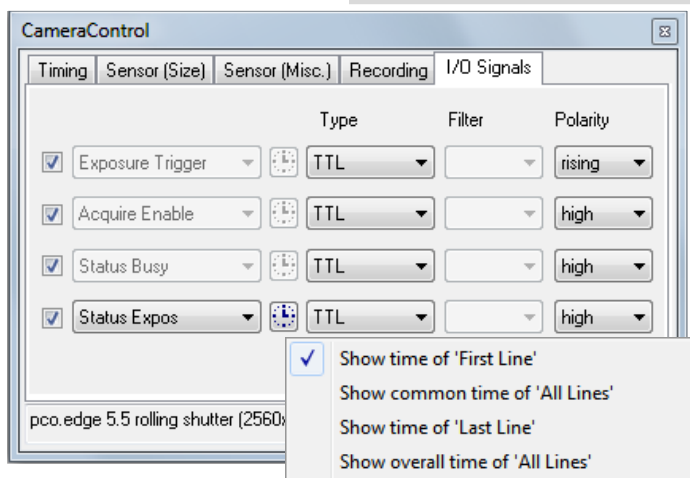
Polarity

active for high/low signal
or rising/falling edge
Maximum low level: 0.8V
Minimum high level: 2V
Slew Rate >1ms/V

Type

TTL Electrically grounded, no opt coupler.
3.3Volt LVTTTL out , short time short-circuit-proof.
Continuous overvoltage withstand: +10V and -5V.
1ms pulse overvoltage withstand: +33V and -33V
ESD pulse: +- 4kV

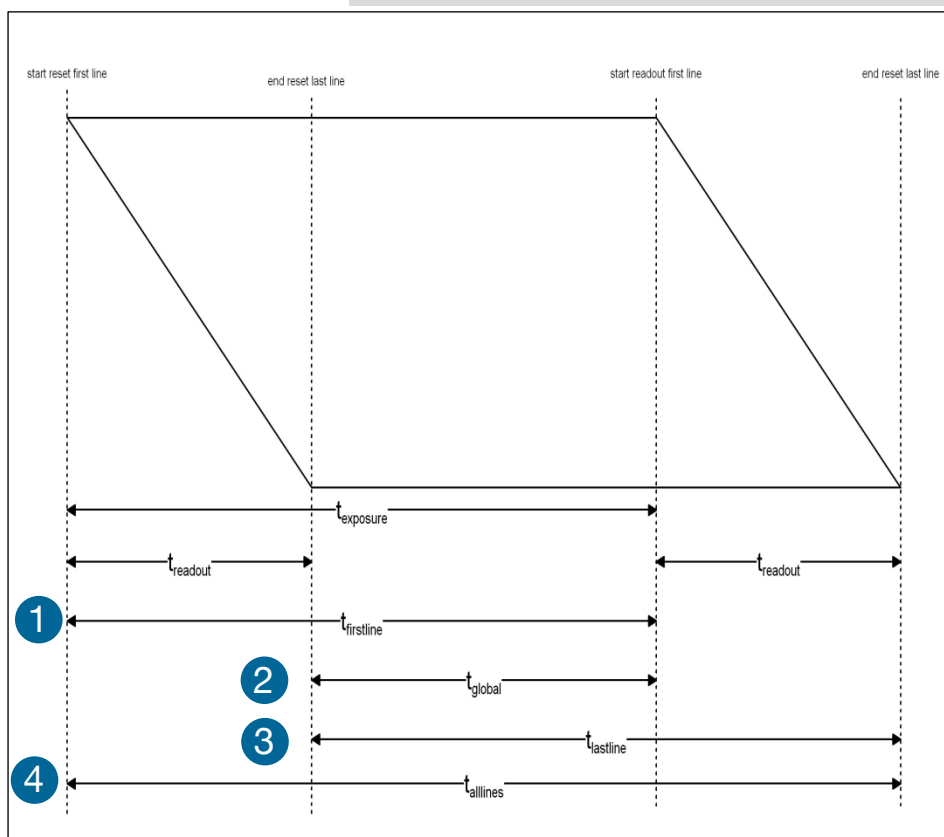
Rolling Shutter Signal Type



At the I/O-signal tab Rolling Shutter signal type options are available (only Status Exposure and if Shutter is set to Rolling Shutter, see Setup 7.4).

There are four signal types available:

- 1 Shows the exposure time of the first rolling shutter line ($t_{\text{firstline}}$)
- 2 Shows when all sensor lines are integrating (t_{global})
- 3 Shows the exposure time of the last rolling shutter line (t_{lastline})
- 4 Shows if any sensor line is integrating (t_{alllines})



7 CAMWARE FEATURES

camware
for SensiCam, PixelFly and pco.camera

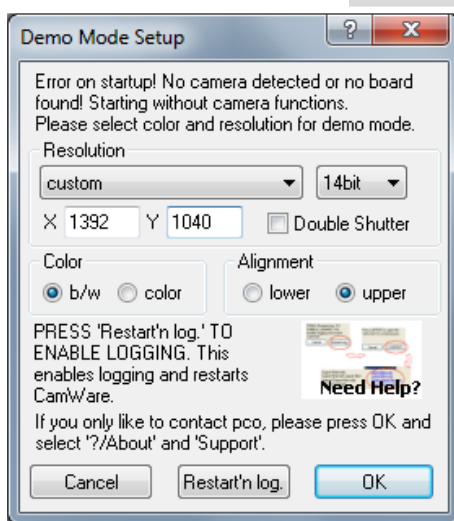


PCO's excellent software for camera control, image acquisition and archiving of images in various file formats.

You will find a **Help file** under the common Help (?) menu.

There are some features explained in the Help file that are not applicable for this camera version.

7.1 IF NO CAMERA IS DETECTED (DEMO MODE)



When CamWare is started, it automatically recognizes the camera type of the connected and running cameras.

CamWare will start in Demo Mode, if your camera is switched off or no camera is connected

In this mode all **image processing** features are available, but all **camera settings** are deactivated. The user only has to tell CamWare what type of image he wants to open. For that purpose, the **Demo Mode Setup** window opens and asks for the corresponding input.

Need Help? If this window pops up because you have trouble running the camera, please see instructions in appendix **A9**.

Resolution

The drop down list displays the existing image sensor spatial resolutions of all PCO camera systems. Please select the specific resolution and bit depth of the images to be opened. If double shutter images have been recorded and should be opened, Double Shutter Mode should be checked.

Color

With the radio buttons, the user can specify whether the image type is monochrome (b/w) or color.

Alignment

These two radio buttons adjust whether MSB (most significant bit) aligned (upper) or LSB (least significant bit) aligned (lower) images have been stored (see **7.3 File Settings**).

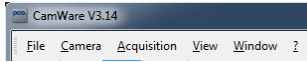
Example settings to view the b16 files of the pco.edge:

Camera	Resolution	Bit	Double Shutter	Color	Alignment
pco.edge 5.5 color	2560x2160	16	No	color	-
pco.edge 4.2 mono	2048x2048	16	No	mono	-

7.2 OVERVIEW



Menu Bar



See chapter **7.3- 7.8**

Local Menu



Mouse right-click is explained in chapter **7.9**

Toolbar



Prints the currently displayed image or comment window

Opens a **b/w | color display** window

Opens the **camera control** window (see chapter **6**)

Opens the **convert control** (see chapter **7.6**)

Auto range peak/crop (see chapter **7.6** Convert Control)

Live preview (see chapter **5.2.**)

Soft trigger captures a single image (see **6.2**)

Cursor display

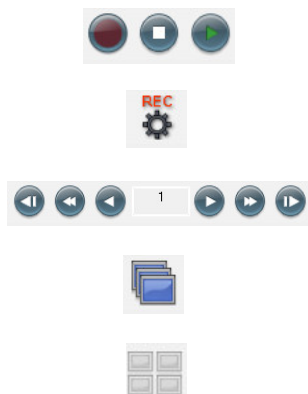
B/W x:1007 y: 13 Value: 263



Cursor: pixel position and intensity value

Continuous **auto range crop** scaling

Recorder



Record **START / STOP / PLAY**

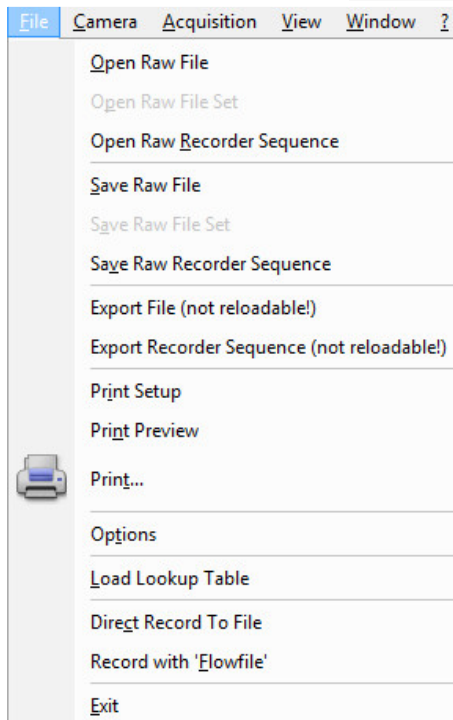
Opens the **recorder settings** window (see **7.5**)

Replay navigation

Image Browser: overview of the recorded images (see **7.6**)

Multi Frame Window (see chapter **7.6**)

7.3 THE FILE MENU



NOTE

Be aware of the different storage abilities of the formats, for example *.bmp - the bitmap format only allows for 8bit values to be stored and therefore the image content of a 16 bit image is reduced, if stored as bitmap.

Open RAW File (single image only)

This command should be used to import a single image into the currently active image window. Only files with the extension and format of ***.b16 (=PCO proprietary binary image format)** and *.tif (TIFF image format) can be imported. If the recorder is enabled, each imported image will be transferred to the buffer shown in the picture number. The image itself will be fitted to the current image size. If the recorder is disabled, the current image sizes will be set to the parameters of the imported image.

Open RAW File Set (only for pco.hsfc pro camera)

Open RAW Recorder Sequence (image sequence from one camera)

This command is used to import a sequence of images. If more than one camera is connected and an image window is currently open, the sequence will be loaded to the active window. If no image window is open, the images will be loaded to camera #1. This command opens the Open file dialog box. Only files with the extension and the format of *.b16 and *.tif (TIFF16) can be imported.

Save RAW File (single image only)

This command should be used to save the image, which is displayed in the active window. The command opens the Save file dialog box. The image file can be saved in 16bit *.b16 and *.tif format. If more than one camera is connected, it is possible to save all current images by selecting Export all images in the Save file dialog box. With this feature it is possible to save one image of each active camera within one process step (it is not necessary to repeat the save process for each camera). The Save command will not be available, if no image window is open.

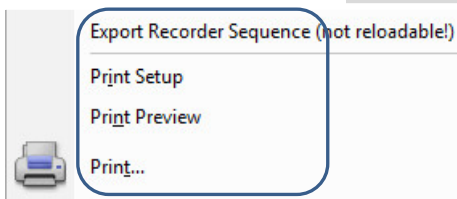
Save RAW Set (only for pco.hsfc pro camera)

Save RAW Recorder Sequence (image sequence from one camera)

The Save Recorder command should be used to save or export image records. If more than one camera is connected and an image window is currently open, the record of the active window will be saved. The command opens the Save file dialog box. The Save Recorder command will not be available, if no image window is open.

Export File (not reloadable!)

Use this command to export the image of the active image window. This command will open the Save file dialog box. Files with the extensions fts, tif, bmp, asc, jpg, and jp2 can be exported. This item will not be visible, if no image window is open



Export Recorder Sequence (not reloadable!)

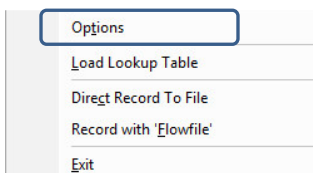
Use this command to export a sequence of images. If more than one camera is connected and an image window is currently open, the record of the window which has got the input focus will be saved. If no image window is open the images of channel 1 will be saved. This command will open the Export image dialog box. Files with the extensions fts, tif, bmp, asc, avi, mpg, jpg, jp2, and wmv can be exported. (see Appendix A8)

Print Setup

The Print Setup command opens the Windows Print Setup dialog box for adjustments and settings of the connected printer(s).

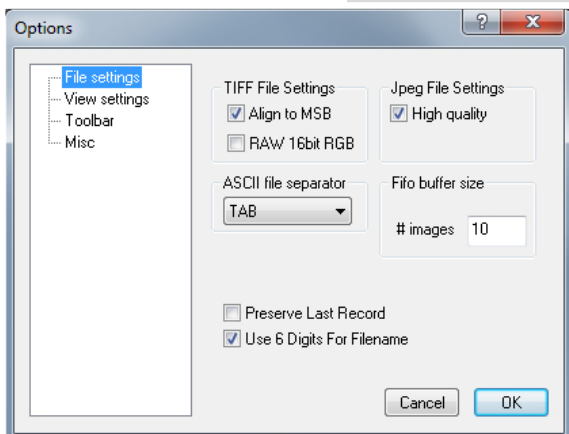
Print Preview This command opens a Print Preview window.

Print Opens the Windows Print dialog box.



This command opens the **Options dialog**, allowing special settings.

File Settings



Tiff File Settings: Align to MSB

Here you can select the alignment of the pixel value, if the pixel depth is less than 16 bit (e.g. MSB: each pixel value is shifted from bit 12-1 to bit 16-5 in case of 12 bit). This removes the dark image effect inside other image applications.

Tiff File Settings: RAW 16bit RGB

Here you can select whether the 16bit RGB tiff file is saved with 16bit raw or white balanced data. If this item is checked, each 16bit RGB pixel value is saved as raw 16 bit RGB (48 bit) value, without white balancing. Saving to 16bit RGB can be done by selecting the color display window, export recorder, selecting 8bit-tiff and checking **Save 16bit RGB**.

ASCII file separator

Here you can select an appropriate separator for the ASCII file format.

JPEG File Settings

Here you can select the quality of the saved jpeg/jp2 files: high quality saves images with 100% quality (otherwise 85% quality).

Preserve Last Record

If checked, a message box will pop up in case the user may overwrite or loose data.

Options
Load Lookup Table
Direct Record To File
Record with 'Flowfile'
Exit

Use six digits for filename

If you record a sequence of *.b16 files and choose direct record to file CamWare is always using six digits for filename (e.g. t_123456.b16).

View Settings

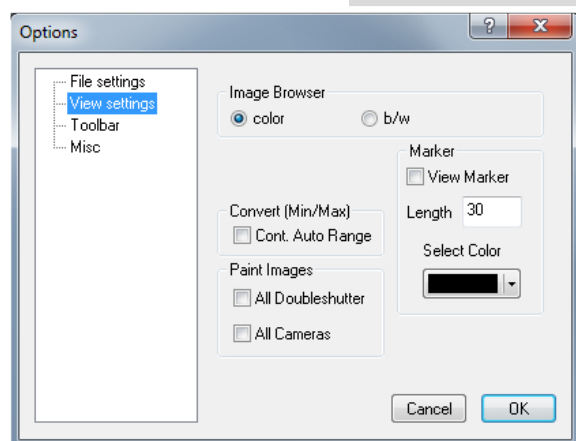


Image Browser

Here you can select between showing all image tiles inside the browser window either b/w or color. Setting b/w will result in a faster refresh, (valid only for color sensor).

Convert (Min/Max)

(Continuous Auto Range Crop, see chapter 7.6 Convert Control BW) This option enables the automatic min/max function during record and replay. Disable this feature if the application stops responding during this mode (due to operating system capacity problems).

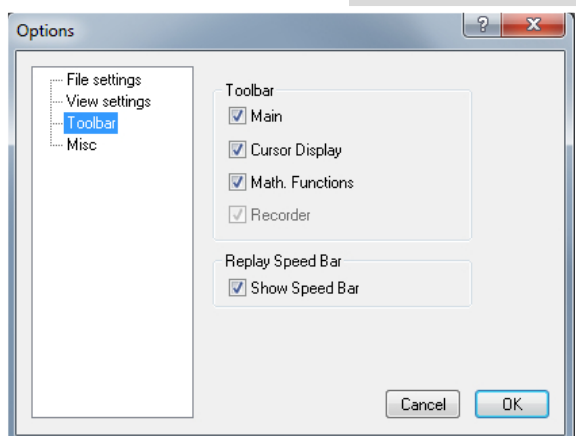
Marker

Use this command to display a crosshair in the center. It is possible to adjust length and color of the crosshair.

Paint Images

This option enables the update of (both double shutter images or) multiple cameras images during record and replay. Disable this feature if the application stops responding during this mode

Toolbar



Toolbar

Opens the corresponding toolbars (see 7.2)

Math. Functions

With the math window you have the ability to build the difference between a reference image and the actual image. If you activate math every new image acquired will be subtracted from the reference image or vice versa.

last acquired image will be copied to reference buffer

a reference picture will be acquired and copied to reference buffer

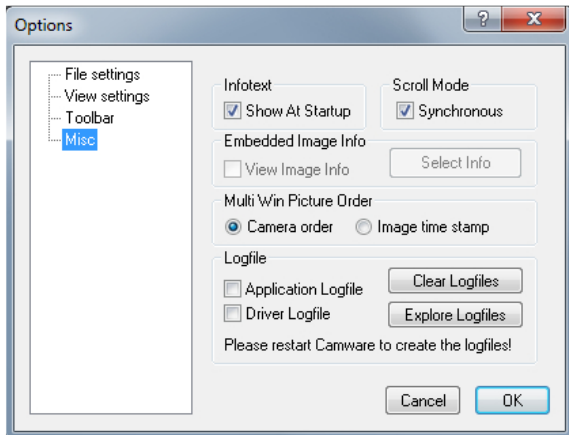
add offset to avoid negative values, which would not be visible

enable / disable math function

Replay Speed Bar

The faster replay speed is useful if large sets of image data need to be scanned.

Misc



Infotext

Use this command to show or hide the start-up information dialog box.

Synchronous Scrolling

If this item is checked all opened image windows will be scrolled at the same time and in the same manner.

View Embedded Image Info (not available)

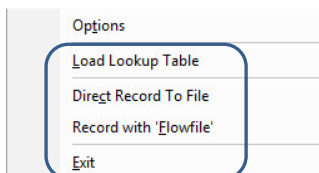
Multi Win Picture Order

With the **Multi Window** you have the ability to view the images of all active cameras in one window.

You can select between **camera order** oriented or **image time** oriented order. **Image time** oriented means that the sequence of images depends on the individual time stamp of each image. **Camera order** oriented means that the first image shown is from camera 1, then camera 2 and so on.

Logfile

This option enables the logging of errors and system info. Enable this feature in order to create a support file, which can help to find out troubles with the camera (see **A8**)



Load lookup Table (for monochrome cameras)

With the Pseudo LUT (Lookup-Table) feature you can load any LUT with one of four different formats and you can view the result in the color view window.

Direct Record to File

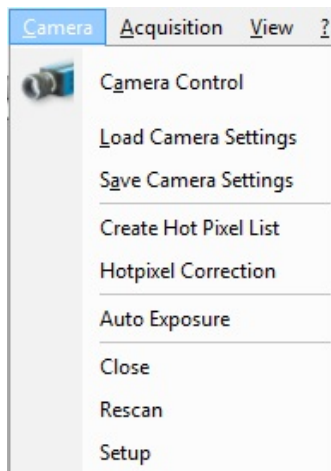
With this command you can pre-set a certain number of images to be stored directly onto hard disk. If the camera captures images faster than the computer can save to disk, then you will lose images. The displaying of the images doesn't interfere with the record process. (See also **6.5** Recorder Mode and PC recommendations in **A5.3** Image Data Flow). Use this command to write data to your **RAID system**.

Record with Flowfile

This command should be used to load a flow file. A flow file contains lines with a delay and an exposure time. Each line corresponds to one image to be acquired. If the flow file has 15 delay and exposure times than 15 images will be acquired. Before the image is snapped, the corresponding time values will be sent to the camera. This affects the possible image frame rate, as additional time is required for setting the values between two images. Please see the sample flow files in the application directory (e.g. flow.txt).

Exit This command exits the program and closes all channel dialog windows. Window positions, settings and sizes are stored in the windows registry and will be loaded again at next start-up.

7.4 THE CAMERA MENU



Camera Control

Use this command to open the camera control window (see 6.1).

Load Camera Settings

With this command you can reload camera settings which have been previously saved. You can reload only a file which has been made with the same camera configuration as it was found by the application at start-up.

Save Camera Settings

This command saves the actual camera settings of all connected cameras.

Create Hot Pixel List (for long exposure only – not available)

Hotpixel Correction (for long exposure only)

Sophisticated hot pixel correction is already implemented in the pco.edge camera.

Auto Exposure

Starts some exposures and tries to find an exposure time that captures images with grey values between 1400 and 1500. It re-adjusts the lookup tables in order to display the images with the new settings best. For low light conditions only.

Close

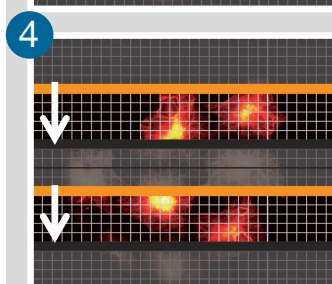
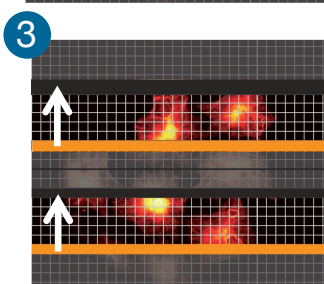
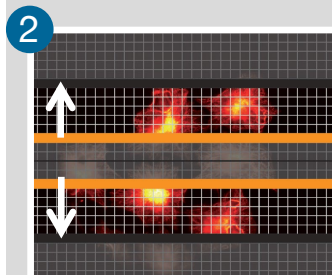
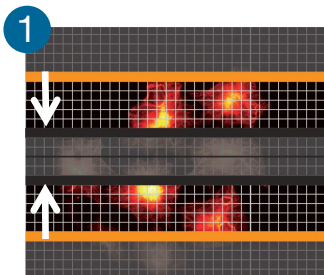
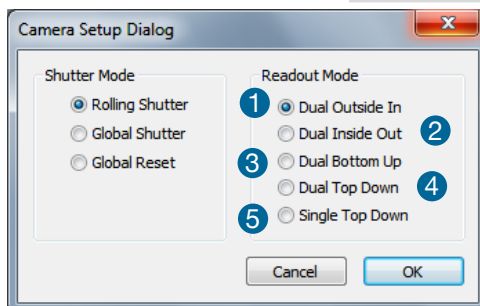
Disconnects camera and switches CamWare to Demo Mode. In case of multiple cameras, all cameras must be closed in order for CamWare to switch to Demo Mode.

Rescan

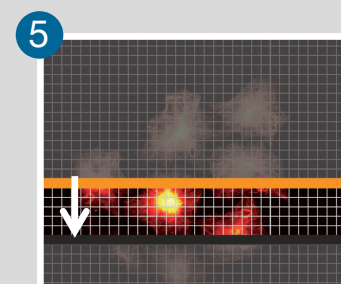
Disconnects and reconnects all cameras.

Setup

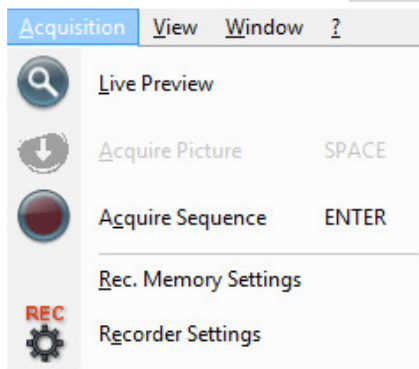
Switch between Rolling Shutter, Global Shutter and Global Reset Mode. The camera will automatically restart.



Only in **Rolling Shutter** (6.2.1) five different readout modes are available. Standard mode is **Dual Outside in**. In **Single Top down**, the pco.edge provides only half of the normal frame rate.



7.5 THE ACQUISITION MENU



Live Preview

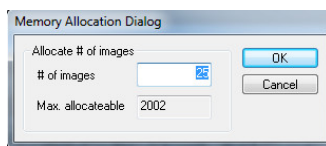
The **Live Preview** is useful for fast and easy adjusting and focusing of the camera. The active window will be updated. To see another window, simply click on the window. This option is not available in double shutter mode.

Acquire Picture (not available)

Records single images in case of sensicam cameras.

Acquire Sequence

Starts recording images into the system memory according to Trigger Mode selection (see 6.2). During the recording, the camera controls are locked.



Rec. Memory Settings

This sets the number of images recorded in one sequence. The maximum is defined by approved RAM size.



Recorder Settings

This command opens the Recorder Settings dialog window.

The **Play Settings** are referred to the camera. If more than one camera is connected, the camera number is retrieved from the image window that has received the input focus (is active). If no image window is opened, the dialog is referred to camera 1. If the **Set to all** checkbox is checked the settings apply to all connected cameras.

The **Global Settings** are valid for all connected cameras.

Averaging

If in the **Avg.** dropdown list a value not equal to 1 is selected, the corresponding number of images is averaged in the buffer, reducing the statistically independent noise.

Another option to reduce the noise is the activation of the **Infinite impulse response IIR lowpass filter**. This filter takes 90% of the previous image and 10% of the new image to create images with clearly reduced noise. $\text{Image (actual)} = \text{Image (act - 1)} * 0.9 + \text{Image (new)} * 0.1$

Replay Speed Slider

The slider can be used to adjust the sequence replay speed, from slow (turtle) to fast (rabbit).

Seq. Wrap Rec

Sequential Wrap Recording sets Recorder Mode (6.5) to Ring Buffer.

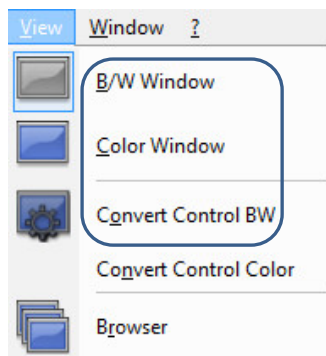
Seq. Wrap Play

The play button starts the display for a sequence as defined by the first image/last image fields and will loop until the stop button is pressed.

Reverse Play

If checked, it is possible to play the recorded images in reverse order.

7.6 THE VIEW MENU



B/W Window

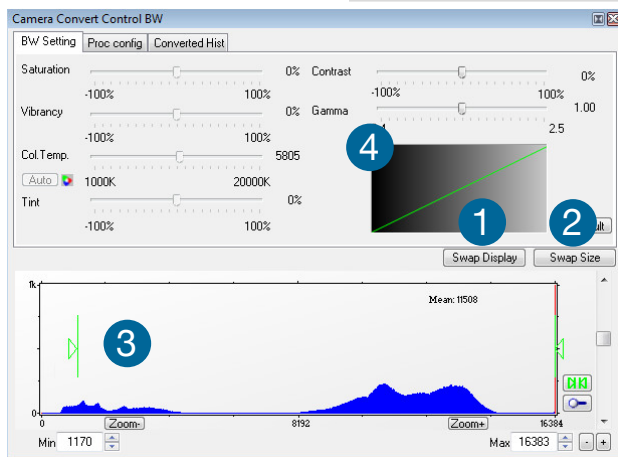
Use this command to open a b/w display window.

Color Window

Use this command to open a color display window.

Convert Control BW

The user can influence how the 16 bit intensity values (x-axis = grey value) of the original image are converted into 8 bit values (y-axis = frequency of the grey value) in different ways.



BW Settings (includes histogram of original data)

It is possible to hide the histogram of original data ① and to switch tab/histogram ②.

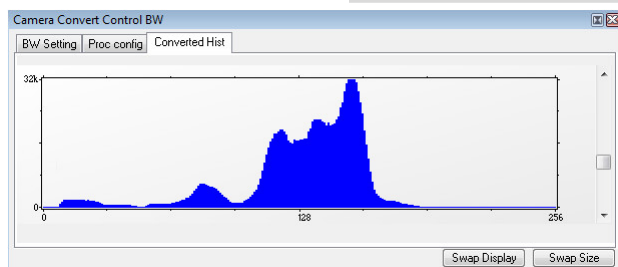
Green sliders in histogram ③

left slider = Min controller (corresponds to value 0 of the 8 bit display). Values below that mark are set to 0, i.e. displayed as black.

right slider = Max controller (corresponds to value 255). Values above that mark are set to 255, i.e. displayed as white.

The values in-between are converted into a value between 0 and 255 according to **Contrast** and **Gamma** settings. See the small **graph** ④, which reflects the calculation.

Proc config tab: please see under Convert Control Color



Converted Hist

This tab shows you the **histogram of converted data**.



How the Auto Range applies



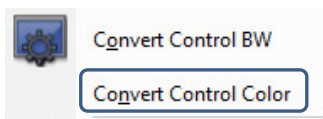
Auto Range Peak searches for the minimum and maximum 16 bit intensity values of the image. Given these number the converter scales the 8 bit display (256) within these two values.



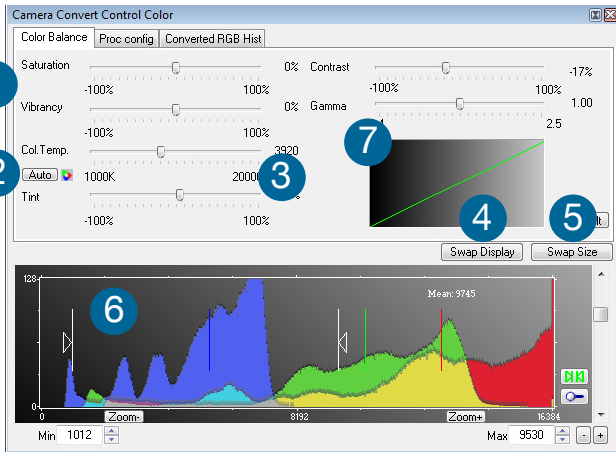
Auto Range Crop sets the converter to ignore the extreme intensity values of the image and scales the display in a smaller range. Thus dark or bright light spots, reflections, etc. are cut off.



Min/Max (Automatic) = Continuous Auto Range Crop



Convert Control Color (only pco.edge color)



Color Balance (Histogram of original data)

Intensity of single color can be controlled by **Saturation** and **Vibrance** **1**.

Press the Auto button to set the **white balance** **2**.

The balancing of RGB can be controlled by **Col.Temp** and **Tint** **3**.

It is possible to **hide the histogram of original data** **4** and to **switch tab/histogram** **5**.

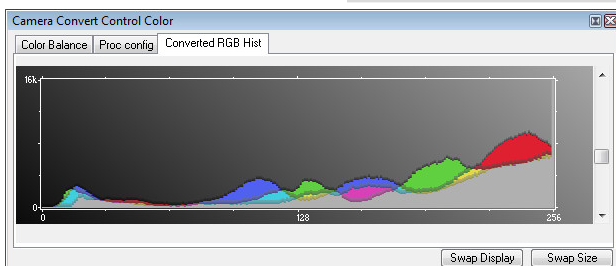
The user can influence how the 16 bit intensity values (x-axis = grey value) of the original image are converted into 8 bit values (y-axis = frequency of the grey value) in different ways.

White sliders in histogram **6**

left slider = Min controller (corresponds to value 0 of the 8 bit display). Values below that mark are set to 0, i.e. displayed as no color.

right slider = Max controller (corresponds to value 255). Values above that mark are set to 255, i.e. displayed as full color.

The values in-between are converted into a value between 0 and 255 according to **Contrast** and **Gamma** settings. See the small **graph** **7**, which reflects the calculation.

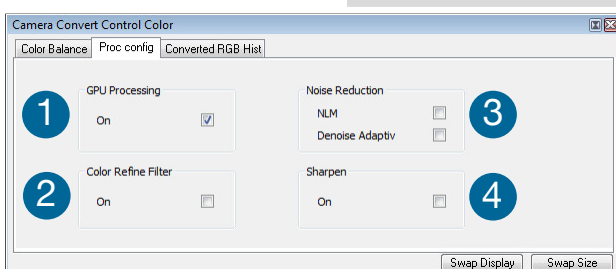


Converted RGB Hist

This tab shows you the **histogram of converted data**.

Proc. Config (Process configuration)

Due to proprietary high-end algorithms used for these image processing features, no detailed description is given here

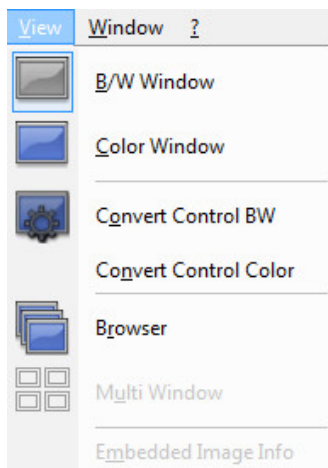


1 switch on in order to significantly reduce processing time

2 pixel color correction

3 non local means algorithm

4 adaptive to brightness and patterns



GPU Processing

In order to benefit from all of CamWare's advanced processing features, we highly recommend a NVIDIA CUDA-enabled graphics processing unit (GPU). AMD's ATI graphics processing units are not recommended.

Find a list of CUDA-enabled products here:

- <https://developer.nvidia.com/cuda-gpus>

Get the CUDA driver here:

- <https://developer.nvidia.com/cuda-downloads>

Make sure:

- that the CUDA driver is successfully installed.
- that the GPU has at least 512MB memory.

CamWare Image Processing

	Color	Monochrome
Pre Processing		
• Noise Reduction	✓	✓
Bayer Processing		
• Bayer Demosaicing	✓	
• Sharpen	✓	
• Refine Process	✓	
• Chroma Blurr	✓	
Post Processing		
• Offset, Gain (Min/Max)	✓	✓
• Color Correction	✓	
• Saturation, Vibrance	✓	
• Color Temperature, Tint, White Balance	✓	
• Gamma, Contrast	✓	✓

Browser

The **Recorder Browser** gives an overview of the images in the Recorder, and helps you in an easy way to select a new current image. Simply click on the desired image to make it the current image. It may then be viewed in the Black/White and Color Window.

The Browser window can show up to 40 pictures per page, thus enabling easy printing of the Browser window. You can switch between the single pages by double clicking inside the Browser window or with the local menu (right mouse button).



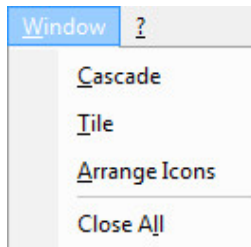
Skip #images allows for convenient overview at large numbers of images.

Multi Window

View the images of all active cameras in consecutive order in one window. Time oriented means that the sequence of images depends on the individual time stamp of each image. Camera number oriented means that the first image shown is from camera 1, then camera 2 and so on.

Embedded Image Info (not available)

7.7 THE WINDOW MENU



Cascade

Show all windows overlapped.

Tile

Tile windows vertically or horizontally.

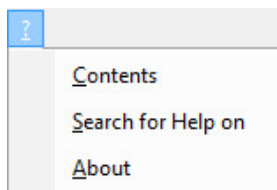
Arrange Icons

Rearranges all minimized topic icons on the desktop.

Close All

Close all windows.

7.8 THE HELP MENU

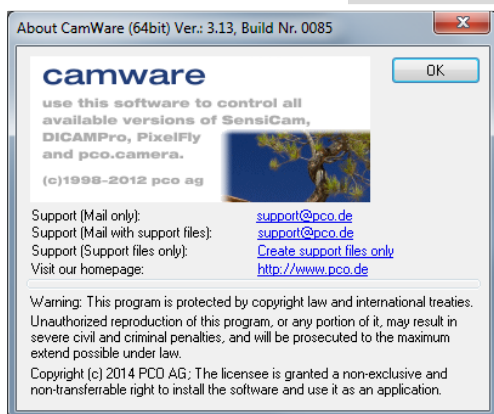


Contents

Opens the main page of the program help.

Search for Help on

Opens an index list for help.



About CamWare

This window shows program information and contains helpful support links. In case of a camera problem, support files (see **7.3 Options/Misc/Logfile**) may be generated, which can be automatically attached to the email. The support files contain relevant hardware information, the log files and the PCO related registry entries. These files are moved into a zip-archive called **CWSupport.zip**, which can be found in the application folder.

7.9 THE LOCAL MENU



The **local menu** is opened by clicking the right mouse button inside the client area of an image window.



Image Properties

Opens an information bubble with main image properties and activates the **in-image display**. It does not overwrite image data.

All camera link cameras generate the image properties out of Camware (Camera Description, see SDK manual for further information) and the PC system time. In case a pco.edge with USB 3.0 interface is connected, the image properties and other metadata is transferred from the camera directly. One additional **line**, which contains all image properties, will be sent from the camera after the image data is transferred.

Image Properties	
Camera Control	
Convert Control BW	
Convert Control Color	
Zoom +	+ Key
Zoom -	- Key
Zoom	▶
Auto Range Peak	
Auto Range Crop	
Auto Balance Color	
Auto Exposure	
Flip	
Mirror	
Rotate Left (90°)	
Rotate Right (90°)	
Line Tool	
Copy To Clipboard	

Camera Control

Opens the Camera Control window (see chapter 6).

Convert Control BW/Color

Opens the corresponding Convert Control windows (see chapter 7.6).

Zoom

Changes the zoom used to display the image.

Auto Range Peak/Crop

Displays the image in a predefined scaling (see chapter 7.6).

Auto Balance Color (only available for pco.edge color)

The white balance feature, which corresponds to the white balance button in the **Convert Control Color** (see chapter 7.6).

Auto Exposure

Auto Exposure feature (see chapter 7.4)

Flip

The image will be flipped before display.

Mirror

The selected image will be mirrored before display.

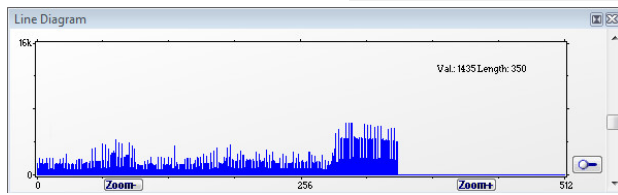
Rotate

The image will be rotated by 90° counter clockwise (left) or clockwise (right) before it is shown in the image window.

Copy To Clipboard

Copies the active image to clipboard (**only as 8 bit image file**).

Line Tool



Select **Line Tool** to show a graph, which shows the intensity of the pixels under the red line shown in the image window. The selection of this menu item determines the location of the first point. After this you can move the mouse to the second point, which can be selected by a **left click**. Now a **Line Diagram**

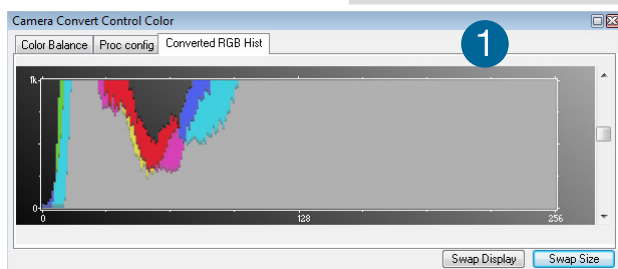
opens and the length of the line (unit: pixel) is shown in a bubble and displayed in the window.

7.10 ADDITIONAL FEATURES

White Balance by Mouse

It is possible to change **white balance** easily by mouse: You only have to press the CTRL (Strg) and the shift button at the same time and select a white or gray area within the image. The pixel values within the coordinates of the selection rectangle are used for calculating a new **white balance**.

For best results we recommend to use the white balance button in the Convert Control Color (see 7.6) or the Auto Balance Color in the Local Menu (see 7.9) respectively.



Fold Up Window

The Convert Control windows can be minimized / folded up **1**. Just move the pointer over the bar and the window will unfold again **2**.



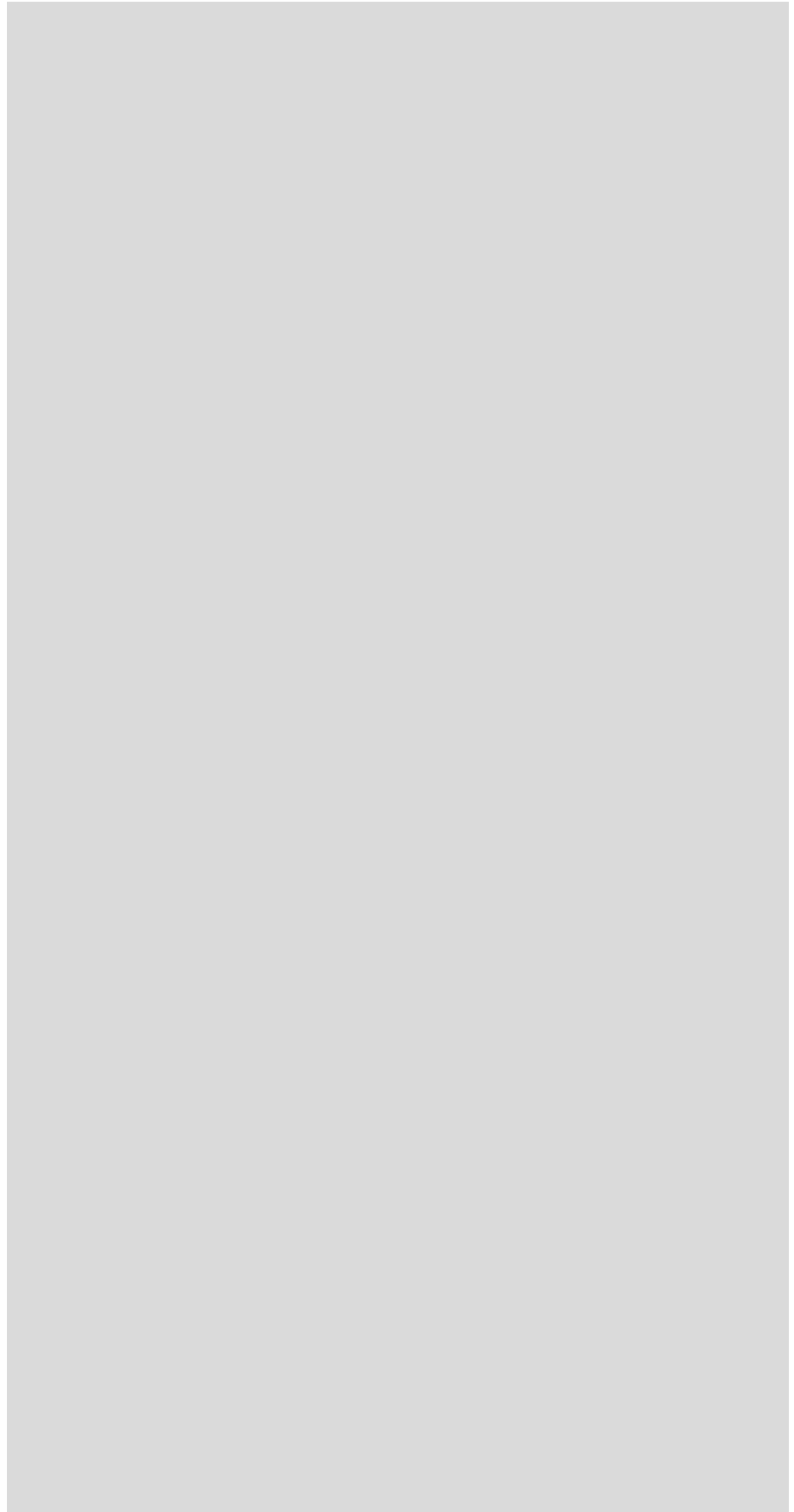
Setting Contrast Area by Mouse

You can control the minimum and maximum values used for the conversion from 16 bit to 8 bit with the mouse. Move the mouse cursor into a region which should be shown with maximum contrast. Press the shift and the left mouse button. Hold down the mouse button while increasing the size of the selection rectangle with mouse moves. After releasing the mouse button the coordinates of the selection rectangle act as a border for calculating the minimum and maximum values.

Setting a new ROI by Mouse

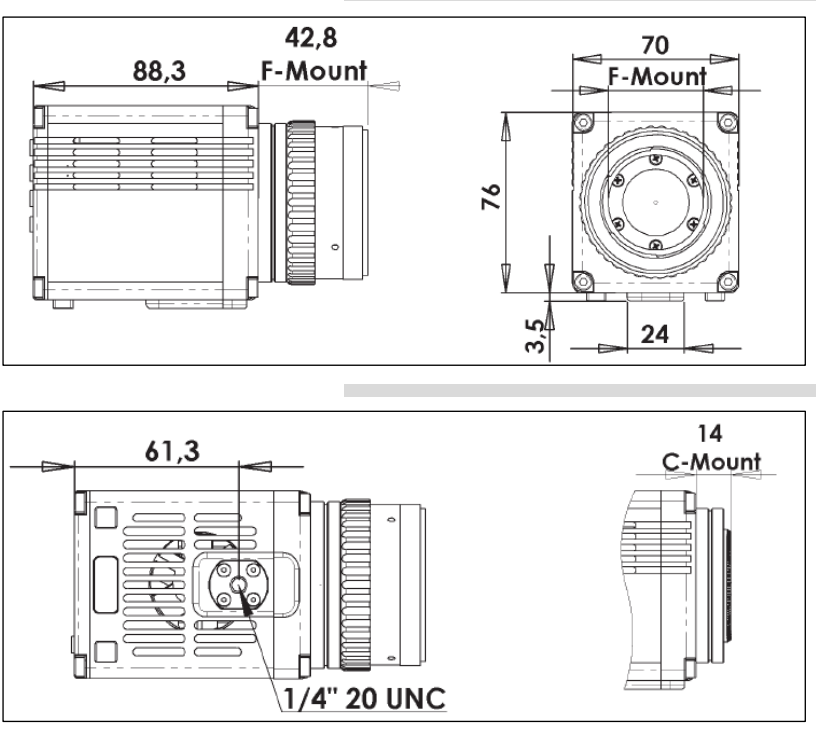
In the same manner you can setup a new region of interest (see **ROI 6.2**) for the camera. You only have to press the CTRL (Strg) button and drag an area with the left mouse button instead of the shift button. The coordinates of the selection rectangle are used for calculating a new region of interest, which will be adapted to the camera capabilities automatically. You can reset the ROI to maximum by pressing the CTRL (Strg) button and the right mouse button.

APPENDIX

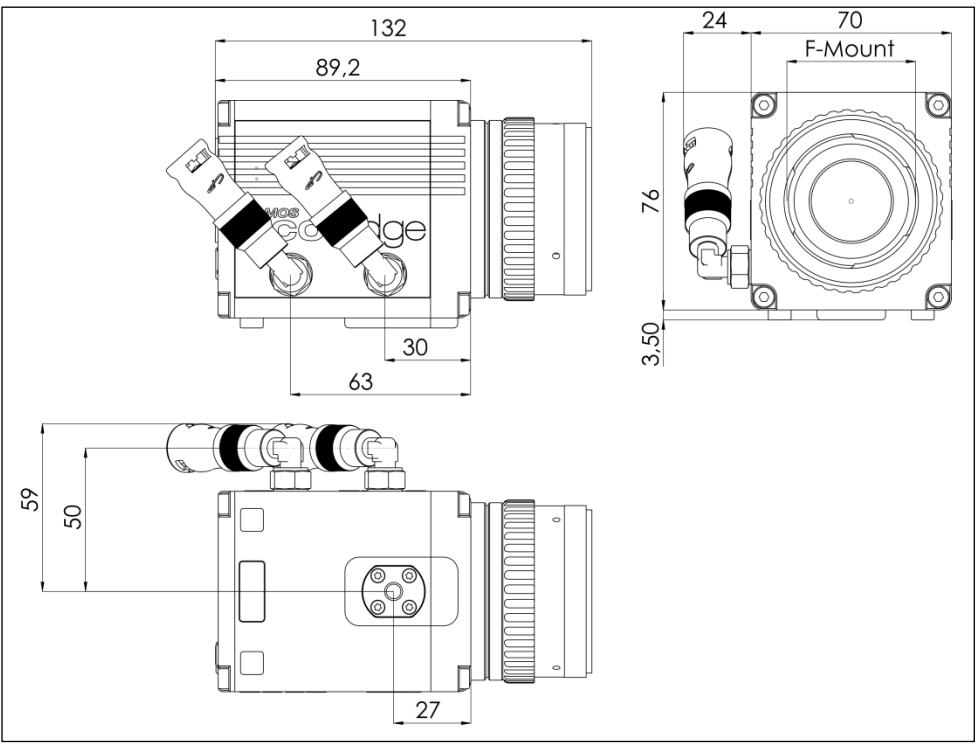


A1 MECHANICAL DIMENSIONS

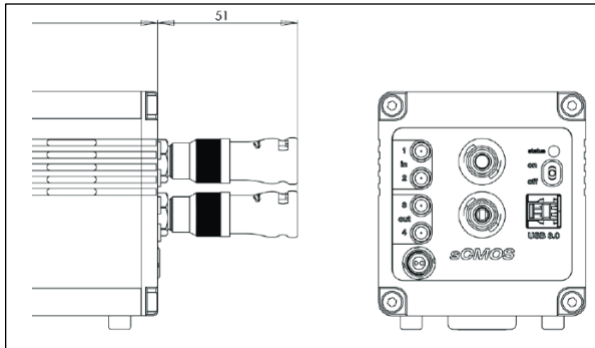
Standard Version (pco.edge 4.2 / 5.5: Camera Link or USB 3.0)



Water Cooled Standard Version (pco.edge 4.2 / 5.5 Camera Link)

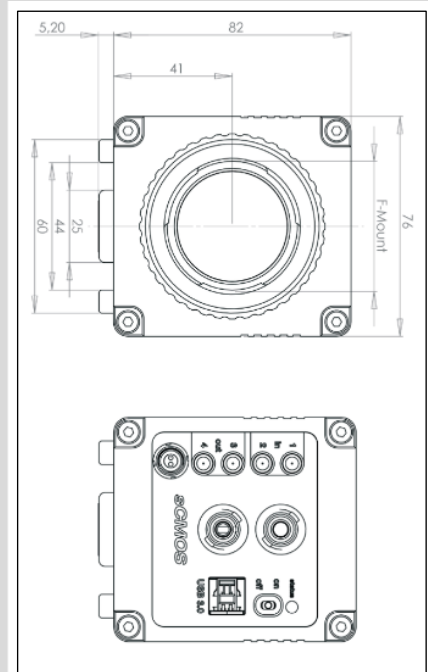
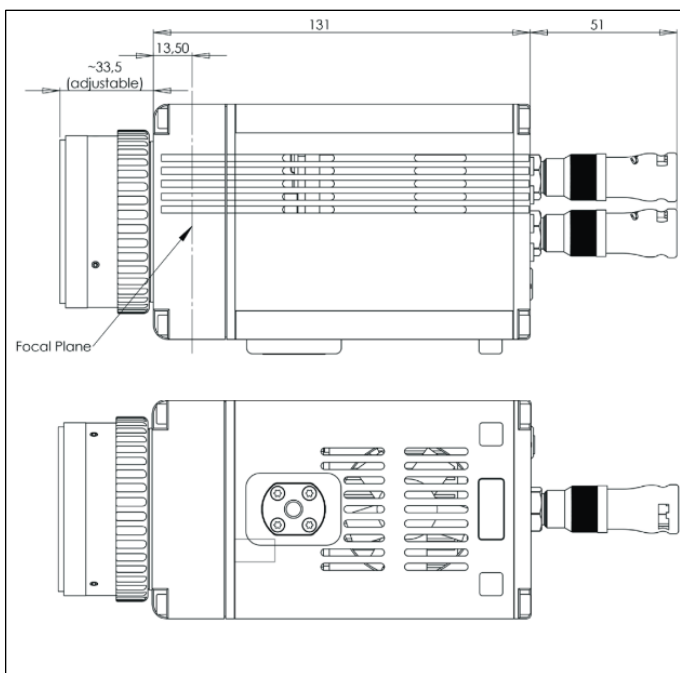


Water Cooled Standard Version (pco.edge 4.2 / 5.5, USB 3.0)



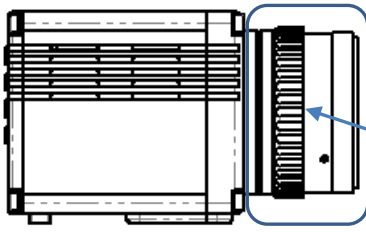
The housing size is similar to the dimensions of the standard version, except the camera design with the USB 3.0 interface allows to locate the water connections on the back of the camera.

pco.edge GOLD series (USB 3.0)



A2 CHANGE FROM F-MOUNT TO C-MOUNT

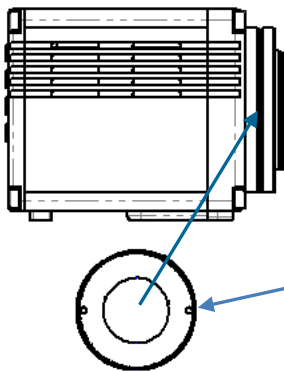
Instructions on how to change the optical input from **F-mount to C-mount**:



Step 1: Remove F-mount Adapter

Grasp the F-mount adapter at the blue ring (counter ring) and turn it counter clockwise.

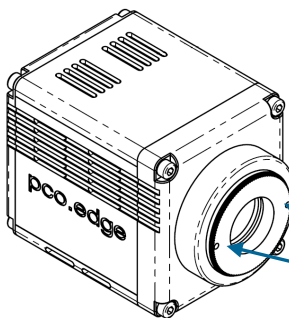
F-mount adapter



Step 2: Insert C-mount Ring

Carefully screw the ring completely in and tighten the two **Allen screws**.

C-mount ring



Adjust Back Focal Length

First of all, attach a lens to your c-mount adapter. Then set the focus of your lens to infinity. After that, look for a point in infinity and generate a sharp image by turning the smaller ring of the adapter. Then fix this position with the two small indented screws.

Allen screws



Limitations of c-mount lenses

Keep in mind that c-mount lenses could cause shadings at the edges of big sized sensors. Most c-mount lenses are able to illuminate a maximum image circle of 11 mm (2/3"), 16 mm (1") or 22 mm (4/3") diameter only. The pco.edge cameras have a sensor diagonal from 18.8 to 21.8 mm, it follows that you have to use the ROI function for a shade less image while using the c-mount adapter with the two smaller C-mount diameters.



A3 USB 2.0/3.0 FOL EXTENDER



The **Adnaco-SU1** is a FOL Extender for USB 1.1./2.0/3.0 devices. It contains two components: the **Adnaco-UT1** (USB Converter) with power supply and the **Adnaco-UF1** (active USB 3.0 FOL cable (integrated electrical optical converter with length of 10, 30, 50 and 100m).

The UT1 transmits signals from USB 1.1/2.0/3.0 to USB 3.0 and has two Type-A USB connectors named **Host** and **Device** and a 5.0V power supply device. The **Host connector** has to be linked with the **UF1 USB 3.0 FOL cable** and this cable has to be connected directly to the computer.

The **Device connector** has to be connected with the pco.edge usb camera.



If you **confuse** the connections, the camera will **not** be identified by your computer. There shouldn't be any damages to your devices if you confuse the connections.

The UF1 is a pure USB 3.0 cable and is built up symmetrically and therefore it is not possible to confuse the connections or to connect the pco.edge (which has a USB Type-B connector) with this cable.

This system only works at a computer with USB 3.0, your camera will not be identified if you connect it to a USB 2.0 connector.

The Adnaco-SU1 is an optical insulator and also gives you the opportunity to physically extend the transmission path between camera and computer.

Performance

If you use a USB 2.0 device at the Adnaco SU-1 a maximum data transfer rate of 24.5 Mbytes/s will be reached.

Cable length	USB 3.0 ^{*1}	USB 2.0 ^{*2}
USB Configuration Without SU-1	357 Mbytes/s	40.1 Mbytes/s
SU-1 10m cable	352 Mbytes/s	24.5 Mbytes/s
SU-1 100m cable	330 Mbytes/s	23.4 Mbytes/s

^{*1}: e.g. pco.edge

^{*2}: e.g. pco.pixelfly usb

A4 WATER COOLING OPTION PCO.AQUAMATIC II

A4.1 SYSTEM COMPONENTS



This is the re-cooling system for pco.edge cameras with water-cooling.



	Material No.	Description
1	30108000211	pco.aquamatic II
2	30108000212	Connection Tube 5m PVC 3541-01 PCO (with Colder NS212 fittings)
3	50402000055	Power supply ETC 70-12 1.2m
4	20307500024	Power cable
5	10307000130	EDGE WAT camera cable 5m FGG-RG58-NC3MX
6	10305000190	Innovatec Protect IP 1L

The operation of the **pco.aquamatic** is simple and uncomplicated. Normally no maintenance and nearly no attention are needed. Only the liquid level of the reservoir (water tank) should be controlled from time to time.

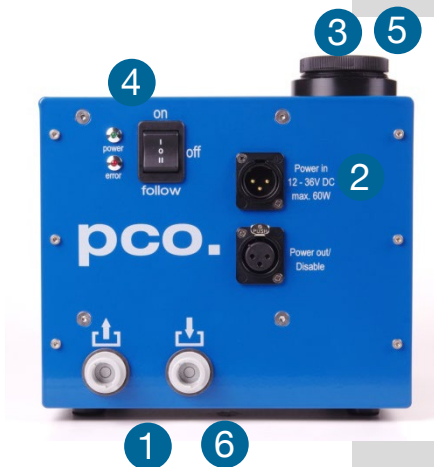
Only use Innovatec Protect IP for the pco.aquamatic! Do not use or add any other cooling liquid or normal water! If you need to add cooling liquid in order to maintain level in the tank, please contact PCO for additional supply.

The cooling liquid will turn yellow after some hours of operation. This is normal and no sign of wear or malfunction. The optimum pH-value is between 8 and 9 (please check this value if you are concerned about the cooling liquid quality).

NOTE

The recommended service interval for the change of the cooling liquid is four years.

A4.2 FIRST TIME INSTALLATION



Please take care to situate the unit on a flat and firm surface. Do not cover the air intakes of the unit. Please ensure free airflow around the pco.aquamatic to ensure maximum cooling performance. All tubes and power cords need to run kink-free.

Before installation of the unit carefully read the **Innovatek Protect IP safety** datasheet (see Innovatek Website).



outlet flow



inlet flow

Please follow steps 1 – 6.

- 1 Connect tubes to cooling unit and camera. The two arrows on the housing of the cooling unit only indicate flow direction. Either connection of the camera can be used for **in** or **out**.
- 2 Attach power connection.
- 3 Open tank cover.
- 4 Turn power switch to **on** position (I).
- 5 Slowly fill in the cooling application mixture while the unit is running, you have to constantly refill liquid.
- 6 While the cooling liquid flows back to the reservoir make sure that the whole air escapes from the system – this takes a few minutes (move hoses if necessary).

The cooling liquid reservoir (tank) is filled when liquid level is approximately 1-2 cm from the top of the tank. The integrated pump only works when the pump chamber is completely filled. To ensure this please move hoses or remove air by evacuating. Reservoir capacity is approximately 500 ml.

After **steps 1 – 6** are completed successfully the system is ready for **operation**.

NOTE

The hose connectors are waterproof in not connected state. Maybe they lose one drop of cooling liquid from time to time. You don't have to empty the hoses while storing the camera system.

A4.3 OPERATION



First connect the **power out** of the cooling unit with the **power in** of the pco.edge camera by using the *PCO WAT camera cable*.

The cooling unit provides two operation modes.

Operation Mode on: the cooling unit is turned on permanently and provides the camera with power. Your camera can be switched on and off as needed.





Operation mode follow: the cooling unit will turn on when the camera is switched on and vice versa.

Error Codes

The coolant temperature sensor is located in the water tank.

Temperature	Action
27°C	fan turns off
36°C	fan turns on
55°C	warning message
60°C	error message

If a **warning level** is passed, the Power LED blinks slowly and the Error LED displays the error code. If a **failure level** is passed, the Power LED blinks fast and the Error LED shows the error code.

 power	 error	Error / Failure
on	off	none
1Hz flash	one short flash	Warning when temperature at 55 °C (also if sensor is defect or missing)
2Hz flash	one short flash	Failure when temperature at 60 °C
1Hz flash	two short flashes	Fan speed (also if a high deviation of the standard value is reached)

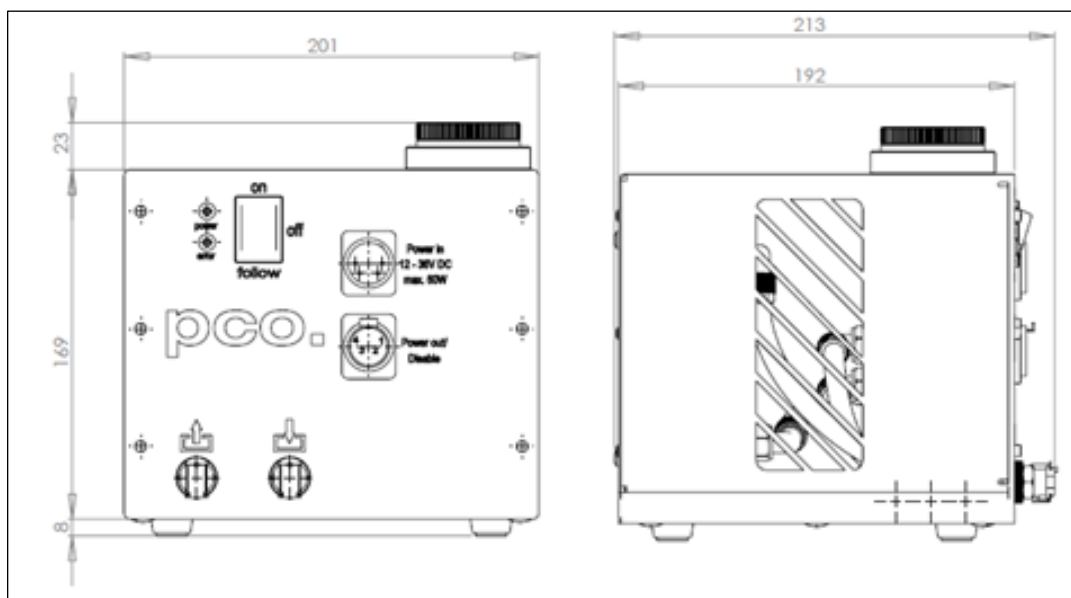
NOTE

The camera has its own protection circuit and will shut down automatically when the electronics temperature exceeds safety level.

A4.4 DIMENSIONS

All dimensions are given in millimeter.

Weight: 4kg (completely filled cooling liquid tank)



General Information

You are not restricted to purchase the pco.aquamatic system - it is possible to use an own water cooling solution. A separate power supply will be provided to every pco.edge camera with water connectors. The hardware of the pco.edge cameras with USB 3.0 Interface is designed to work with or without a water cooling system, because a fan that provides adequate cooling is inside the camera anyway. Please note, that the minimum sensor temperature of the pco.edge GOLD series is depending on the cooling system.

In case you use an own water cooling system, please make sure that the liquid you use to cool your camera is at all times NEVER below the dew point of the ambient temperature! In order to avoid any appearance of condensation, use a cooling liquid at room temperature. A liquid flow rate of 1-2 litres per minute is sufficient.

A5 CAMERA LINK

A5.1 INSTALLATION OF THE GRABBER CARD

NOTE

Hardware Installation must be performed by a technician, because high voltages can occur on the device. Always pull the main plug before opening the device.

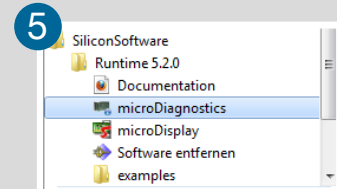
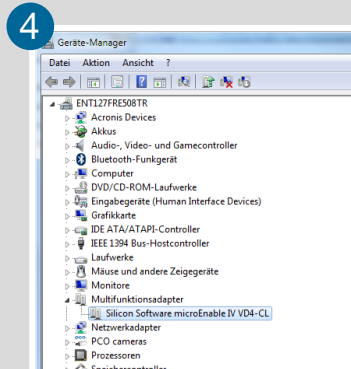
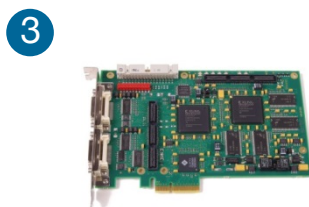
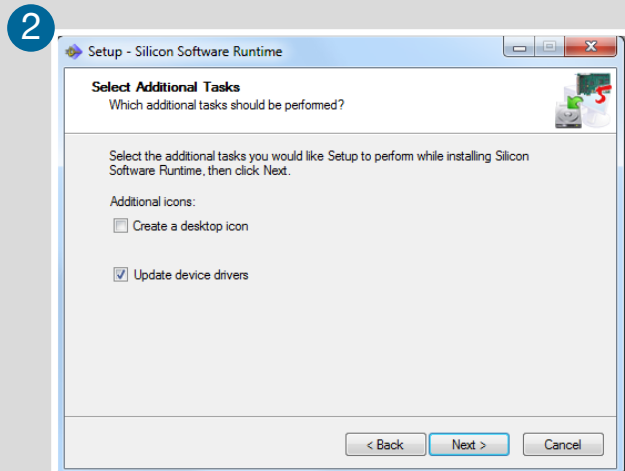
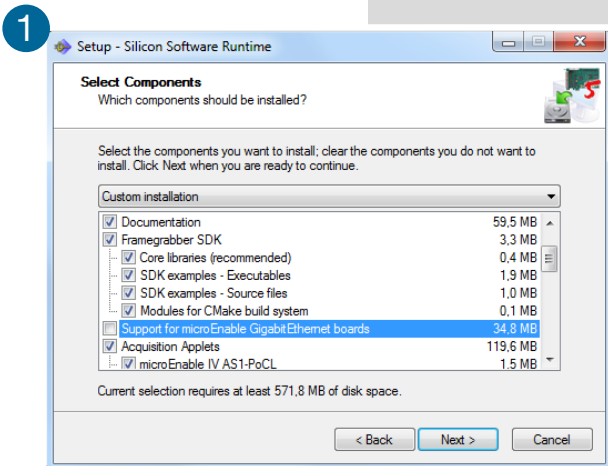


Instructions for installing and testing the **SILICONSOFTWARE microEnable IV (ME4)** Camera Link grabber card

Please install the latest silicon software runtime package before installing the hardware. (Download: www.pco.de/support)

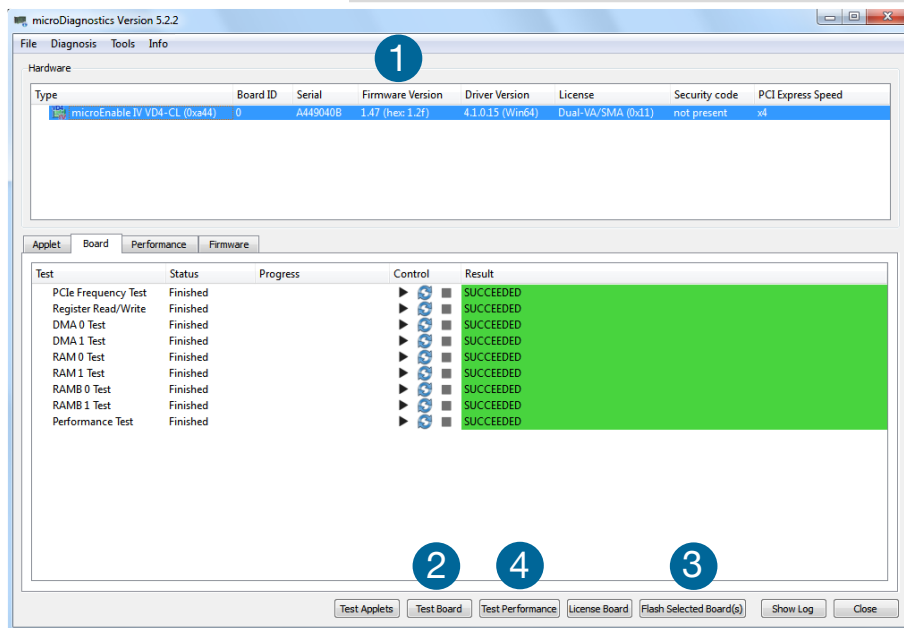
When working on a 64 bit operating system, please make sure to install the proper (64 bit) runtime when also a 64 bit application will be operated. If the application is 32 bit, you need to install the 32 bit runtime accordingly.

- 1 If there is no Gigabit Ethernet board installed (standard), please deselect **Support for...**
- 2 Let the program also update device drivers.
- 3 Shutdown your computer, open the computer case and install the **grabber card**
- 4 The grabber card should be displayed within the device manager. If the device is not shown this way, please reinstall the **SiliconSoftware device driver**.
- 5 After the installation, please start the program **microDiagnostics**. (see next page)



A5.2 MICRODIAGNOSTICS TOOL

How to use microDiagnostics Tool



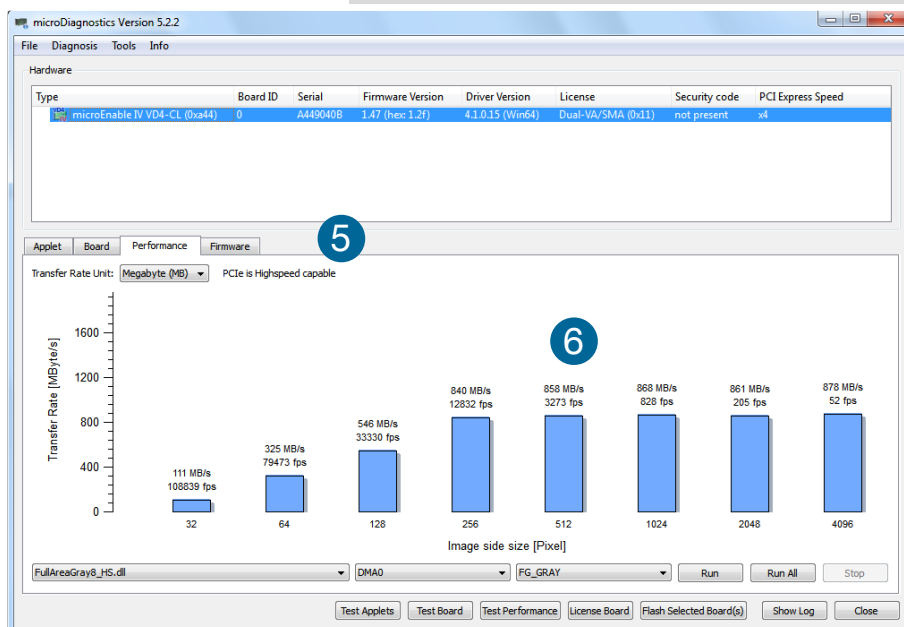
Please verify the firmware **1** version, which must be **1.40** (1.28 in hex) or above.

To test the board, select the board in **Hardware 1** and click **Test Board. 2**

If the firmware is not 1.40 (1.28 in hex), please upgrade to the latest firmware. Select **Flash Board(s) 3** then select the grabber in the dialog and open the appropriate hap file.

Then click on **Yes** when you're asked to proceed. You must power cycle your computer after the upgrade.

In case the firmware version is ok, please click on **Test Performance. 4**



It is mandatory that **PCIe is Highspeed Capable 5** is shown. Otherwise the board is probably not able to transfer the necessary data rate.

The transfer rates, as shown, should be displayed. **6**

For further information or assistance with mainboards please contact our support team.

A5.3 IMAGE DATA FLOW

The **sCMOS image sensors** provide an extremely high frame rate compared to other scientific image sensors. The high frame rate, along with the high dynamic, creates a large amount of data that must be handled and stored. The maximum data rate of the sCMOS image sensor is given by:

pco.edge 5.5 Camera Link:

$$[2560 * 2160 \text{ (pixel in 1 frame)} * 2 \text{ Byte (= 16bit dynamic)}] * 100 \text{ [frames/s]} = 1.1 \text{ GB/s (pco.edge 5.5, Camera Link)}$$

To handle this considerable amount of data, there are **two options** available:

Option 1: Real-time Recording to Computer

The pco.edge sCMOS camera series uses this option. For this purpose, the interface must be capable of transmitting data at the required speed. Interfaces such as GigE, USB 3.0 and Camera Link are not fast enough to transmit this data, which is delivered by the largest sCMOS image sensor. Nevertheless, there is a sophisticated solution that uses the Camera Link interface, which is integrated into the pco.edge camera. It is a fact of nature that light, itself, has its own noise component called **photon or shot noise**, which increases with light signal. In this approach, no compression is made in small signals, while for large signals a suitable compression is applied. Since the introduced compression error is always smaller than the photon noise induced error, it is not seen and a so called **visual lossless compression** has been performed.

It can be shown that this is possible without any significant loss of information. Therefore, the calculation for the pco.edge camera at full speed and full frame has to be re-written:

$$[2560 * 2160 \text{ (pixel in 1 frame)} * 1.5 \text{ Byte (= 12bit dynamic)}] * 100 \text{ [frames/s]} = 0.829 \text{ GB/s}$$

The Camera Link interface can transmit this in real-time. In the future, recently introduced machine vision interfaces including CoaXPress and Camera Link HS are capable of transmitting sCMOS image data without any compression. A network type interface, 10GigE, is similar with respect to hardware to Camera Link HS, but incorporates all of the known GigE advantages and disadvantages. Here, the usual protocols are not favorable for image data transmission, and any network traffic can dramatically reduce available transmission speed. **The real-time data transmission into the computer allows for a variety of applications, since it is free from camera memory limitations.** Image data can be stored directly in the computer's random access memory (RAM) up to more than 64 gigabyte. With an appropriate RAID system, the data can be stored directly to hard disks and there is no delay involved.

Option 2: Recording in the Camera

For high-speed imaging applications where data transfer rates are in the range of several GB/s it is accepted that the primary image memory (camRAM) must be located in the camera. Two examples of

such high-speed cameras are the pco.dimax with 36 GB of camRAM and the pco.dimax HD with 18 GB of camRAM memory. This allows for fast recording, but just up to the integrated memory limit. Before a second sequence can be recorded, one must endure the wait time until data is downloaded to computer storage. Therefore, this option can only be used for recording short sequences with enough time between each event to download the image data. This option is not necessary for the pco.edge as either with USB 3.0 or Camera Link interface, the image data will be recorded to the computer in real-time.

Memory Structure / Organization

As the memory is software-controlled in both options, it does not matter how the data is stored. The memory can be organized for ring buffer or FIFO recording, or for a specified number of images like a burst mode. The pco.edge camera enables all of these possibilities with the integrated dynamic link libraries and proprietary CamWare application software. This allows the customer to select the memory structure and organization that is optimized for the application at hand.

Recommendations

In the following you can find **two exemplary systems** for RAID and RAM storage options that have been successfully tested by pco for high performance **and which we sell directly to our customers**. They only show a configuration example, for actual system configurations please call us directly.

RAID 0 SYSTEM

11x 2TB SATA 6 GB/s
16 GB DDR3 RAM
Intel® Core™ i7-3820 processor 3.6 GHz
GeForce GTS 640 2GB (NVIDIA CUDA)
Windows 7 Professional 64 bit

RAM RECORD ER

64 GB DDR3 RAM
Intel® Core™ i7-3820 processor 3.6 GHz
GeForce GTS 640 2GB (NVIDIA CUDA)
Windows 7 Professional 64 bit

NOTE

Items are exemplary and subject to change. Please contact PCO for recommendation of current systems and sell of these systems. The use of normal consumer PCs is not recommended!

ASUS mainboards seem to fail generally during the HS-mode test and are not recommended.

Recommended minimum configuration (or better):

- CPU \geq i7 2.5 GHz
- RAM \geq 1066MHz, 8GB
- Mainboard \geq Supermicro X9SRA (socket 2011)

A6 USB 3.0

A6.1 HARDWARE RECOMMENDATIONS

The pco USB 3.0 interface is based on the Cypress EZ-USB FX31 device and it is compatible to pco software such as CamWare and SDK. To run a pco USB 3.0 camera successfully the user should consider a number of important issues that are discussed in the following chapters.

Motherboard and Chipset Configuration

It is recommended to use a Motherboard with a state of the art USB 3.0 host controller for the onboard USB 3.0 ports. The latest generation of USB 3.0 xHCI host controllers manufactured by Intel, Renesas (NEC), Fresco, Via Labs, ASMedia and Texas Instruments Inc. (TI) are tested by Cypress Semiconductor Corporation. (see Cypress EZ-USB® FX3TM SDK Release Notes, Version 1.2.3, chapter 1.3). Currently pco recommends only motherboards with the following onboard xHCI host controllers:

- Renesas/NEC µPD720202 Host Controller
- Intel® USB 3.0 eXtensible Host Controller

If the motherboard does not have an onboard USB 3.0 port or the onboard USB 3.0 port does not work properly with a pco USB 3.0 camera, ***please use an independent PCIe USB 3.0 extension card.*** In this case, pco recommends the following:

- DELOCK 89348 (U3-PCIE1XG202-10)
PCIe 1x (µPD720202 host controller)
(This board is sent with your pco.edge USB 3.0 camera system as standard)
- DELOCK 89325 (U3X4-PCIE4XE101)
PCIe 4x (µPD720202 host controller)

USB 3.0 extension card with xHCI4 host controller

The following companies manufacture USB 3.0 xHCI host controller:

- Renesas Electronics America Inc. (earlier NEC),
- Texas Instrument Inc.,
- VIA Labs Inc (Diamond),
- Fresco Logic Inc.,
- Intel Inc.,
- AMD Inc. and
- Etron Technology, Inc.

NOTE

To determine suitable manufacturers of the xHCI controller, please use the Windows Device Manager. For example, in Windows 7 drop down the USB Controller entry and find the USB 3.0 host xHCI controller of the USB 3.0 device in the sub-tree. Then right-click to open the properties dialog, click the **details** tab, and choose **Vendor** in the properties pull-down box.

NOTE

USB 3.0 interface cards with controllers from **Etron** Technology, Inc. have not yet been tested.

The following table gives an overview about tested and recommended system configurations or hardware components.

Component	Recommendation
Motherboard	There is no recommendation for a manufacturer. But if an onboard USB 3.0 port is used, the Renesas's xHCI host controller μ PD720202 is recommended.
USB 3.0 extension card	<ul style="list-style-type: none"> • DELOCK 89348 (U3-PCIE1XG202-10) PCIe 1x (μPD720202 host controller), • DELOCK 89325 (U3X4-PCIE4XE101) PCIe 4x (μPD720202 host controller)
PCIe Slot	A PCIe 4x, 8x or 16x slot is recommended.
USB 3.0 Cable	USB 3.0 cable included in the packaging of your pco USB 3.0 camera
USB 3.0 Hub	Not recommended
Operating System	Windows XP 32 Bit, Win7 32 / 64 Bit, Win8 32 / 64 Bit
Multiple pco USB 3.0 cameras connected to a PC	A separate DELOCK 89348 (U3-PCIE1XG202-10) extension card for each camera should be used to guaranty maximum data throughput of each camera.
FOL adapter	See A3

Recommended Software Components

The pco USB 3.0 driver supports Windows 7/8 (x86 or x64) and Windows XP x86 operating systems. Microsoft does not support USB 3.0 natively for Win 7 or older Windows versions. Therefore use the manufacturers' supplied xHCI host controller driver. By contrast, in Windows 8 Microsoft does provide a native generic xHCI Driver but pco recommends using the driver from the corresponding manufacturer of the xHCI host controller. Currently there are seven different vendors producing USB 3.0 host controllers:

- Renesas Electronics America Inc. (earlier NEC)
- Texas Instrument Inc.
- Intel Inc.
- VIA Labs Inc (Diamond),
- Fresco Logic Inc.
- AMD Inc.
- Etron Technology, Inc.

Please make sure that the most recent driver from the manufacturer is installed before a pco USB 3.0 camera is connected to a USB 3.0 port of your computer. The appropriate driver for the USB 3.0 port could be loaded from the website of the manufacturer of the USB 3.0 host xHCI controller; or from the website of the USB 3.0 extension card vendor. The current driver of the extension card included in the packaging of your pco USB 3.0 camera is added to the **pco.USB stick** delivered with each pco.edge.

NOTE

To determine the driver currently in use for the xHCI controller, use the Windows Device Manager. For example in Win 7, drop down the USB-Controller entry and find the USB 3.0 host xHCI controller of the USB 3.0 device in the sub-tree. Then right-click to open the Properties dialog, click the driver tab and choose driver details

Before the pco.edge USB 3.0 camera is connected to the computer the pco USB 3.0 Driver has to be installed. (see 4.1) Please visit the support section of our website to get the latest USB 3.0 camera driver.

A6.2 INSTALLATION OF THE USB 3.0 CARD



NOTE

Hardware Installation must be performed by a technician, because high voltages can occur on the device. Always pull the main plug before opening the device.



An external USB 3.0 Host Controller Card is enclosed to each pco.edge USB 3.0 camera.

Hardware Installation

First shut down your computer and install the USB 3.0 Host Controller.



Driver Installation Instructions

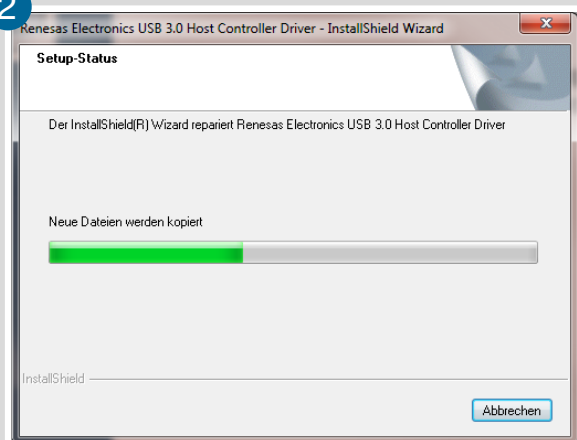
- Within the provided installation files **USB_HBA**, open the folder U3X4-PCIE4XE101, U3X4-PCIE1XE101, U3-PCIE1XG202.
- Open the subfolder Driver and run RENESAS-USB3-Host-Driver-30230-setup.exe.
- If your current OS is Win7/8 and the User Account Control is enabled, a dialog could occur asking, if you wish to launch the setup: Accept with **Yes**.

- 1 At first the installation is prepared.
- 2 Secondly the software components are copied.
- 3 Finally the installation is completed and the **Delock USB 3.0 extension card** can be used.

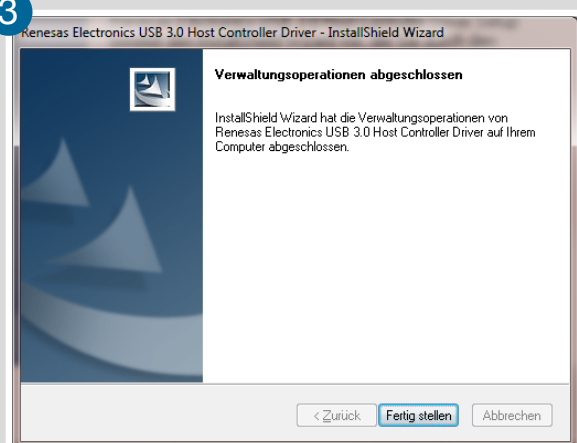
1



2



3



A7 BINNING IN CMOS SENSORS

Binning describes the summation of single pixels to form larger pixels and thereby improve the signal-to-noise ratio (SNR).

Binning in CCD image sensors

The term binning comes from scientific CCD image sensors. The prominent feature of charge-coupled-devices (CCD) is the lossless transport or shifting of charge packages until an amplifier circuit converts them into a voltage at the output, where the main readout noise contribution occurs. If charge packages from two or more pixels are added before they are read out (past the output amplifier) because of very low light signals; this process is called binning. Since the signal is increased before it is read out, and the image sensor's readout characteristics remain unchanged, binning improves the SNR, and the image sensor's resolution is reduced. The lossless transport feature of CCD image sensors makes binning possible.

Binning in CMOS image sensors

In general, binning is not possible in CMOS image sensors because voltages are processed and no charges are transported. In each pixel, the light generated charges are converted into voltages with the readout noise contribution of these amplifiers. Therefore, as opposed to CCD image sensors, if these voltages were combined, the readout noise would also be combined, which would not have the same positive effect on the SNR.

Nevertheless, such a summation or even an averaging would be beneficial for the SNR, but with a smaller impact compared to CCD image sensors. Since such **CMOS binning** cannot be done within the image sensor, it either has to be done in the camera or in the computer.

NOTE

The current default binning mode is accumulation. Averaging is not available within CamWare.

CMOS binning 1 – accumulation: Pixel values can accumulate, causing an effective dynamic reduction or larger number formats, because the result might exceed the original format -- two times maximum 8 bit values will result in a 9 bit value. This will not be a problem if 12 bit values are accumulated and transported as 16 bit images. However, in the case of scientific CMOS, if 16 bit values are transmitted in 16 bit images, only two times 15 bit maximum values are allowed. The signal of the binned pixels will be accumulated, due to the properties of readout noise; the increase of the noise itself will only be as big as the square root of the number of binned pixels. The SNR will improve and in addition, a reduction of the stored image data is achieved.

CMOS binning 2 – averaging: Pixel values can be averaged, which has the same effect on the SNR as accumulation due to the properties of noise. This would keep the image output format the same and would reduce the amount of image data that can be stored. When this type of **CMOS binning** is processed in the camera it is called **hardware binning**. This should not be confused with real binning in CCD image sensors, because the **hardware** that processes this binning is not much different from the **hardware** in computer processing. Therefore, the term **hardware binning** may be misleading.

A8 IMAGE FILE FORMATS

There are different file formats available for saving camera images with CamWare.

b16

The b16 16 bit format is similar to the bmp format. However, 16 bit pixel values are used instead of 8 bit pixel values.

The file format consists either of a Basic Header (6 Long-parameter) or of an Extended Header (32 Long-parameter), the latter of which is optionally for additional information. There might follow a variable comment field (ASCII code). Finally, there is the actual data set that is saved linearly (as in the case of BMP files).

With the exception of the first value, all parameters are Long Integers (4 Byte). The first 6 parameters must always exist. The rest of the parameters, as well as the comment field, are optional.

	Parameter	Function
1	pco-	the first 4 byte are the characters pco-
2	file size	file size in byte
3	header length	header size + comment filed in byte
4	image width	image width in pixel
5	image height	image height in pixel
6	extended header	-1 (true), extended header follows
7	color mode	0 = black/with camera, 1 = color camera
8	b/w min	black/white LUT-setting, minimum value
9	b/w max	black/white LUT-setting, maximum value
10	b/w linlog	black/white LUT-setting, 0 = linear, 1 = logarithmic
11	red min	red LUT-setting, minimum value
12	red max	red LUT-setting, maximum value
13	green min	green LUT-setting, minimum value
14	green max	green LUT-setting, maximum value
15	blue min	blue LUT-setting, minimum value
16	blue max	blue LUT-setting, maximum value
17	color linlog	color LUT-setting, 0 = linear, 1 = logarithmic
18 ... 266	internal use	

Comment file in ASCII characters with variable length of 0...XX.
The length of the comment filed must be documented in the header length field.

	16 bit pixel data
line 1, pixel 1	value of the first pixel
line 1, pixel 2	value of the second pixel
...	...

We recommend that all images should be saved first in the b16 or TIFF format. The advantage is to have the b16 or tiff images available all the time. You will always have the maximum 16 bit information. Please note that not all image analysis programs can accommodate 16 bit data. The 8 bit format saves only the information displayed on the monitor screen. The 16 bit information will be lost and cannot be displayed later.

pcoraw

This 16 bit pco file format is based on the new BigTIFF format, thus allowing for file size > 4GB. A new pco proprietary compression scheme is added in case it is necessary.

Standard File Formats**TIFF**

Tag Image File Format, version 6.0 and lower. There is a 16bit monochrome and color image format.

BMP

Windows Bitmap Format, b/w or color 8 bit format-images, which have been saved in BMP format can be loaded later only as 8 bit images, i.e. part of the original information (16 bit) is lost.

FTS

Flexible Image Transport System, Version 3.1. There is a 16 bit image format. The NASA/Science Office of Standards and Technology (NOST) has defined this format. Some programs use the FIT extension for this format.

ASCII

16 bit format, some mathematical programs prefer ASCII data.

JPG

JPEG (named after the Joint Photographic Experts Group who created the standard) is a commonly used method of lossy compression for photographic images. The degree of compression can be adjusted, allowing a selectable tradeoff between storage size and image quality.

JP2

JPEG 2000 is a wavelet-based image compression standard and coding system. It was created by the Joint Photographic Experts Group committee in the year 2000 with the intention of superseding their original discrete cosine transform-based JPEG standard (created 1992).

AVI

Audio Video Interleave is a multimedia container format introduced by Microsoft in November 1992 as part of its Video for Windows technology.

MPG

MPEG-1, similar to JPEG, is a standard for lossy compression of video and audio developed by the Moving Picture Experts Group (MPEG).

WMV

Windows Media Video (WMV) is a compressed video compression format for several proprietary codecs developed by Microsoft. The original video format, known as WMV, was originally designed for Internet streaming applications, as a competitor to RealVideo.

A9 SERVICE AND MAINTENANCE

Service

The camera is designed to operate with no need of special adjustments or periodic inspections.

Maintenance



Unplug the camera from any power supply before cleaning it.



Use a soft, dry cloth for cleaning the camera.
Do not use liquid cleaners or sprays.

The lens is best cleaned with pressurized air or with liquid cleaners such as pure alcohol or with special optical cleaners that are available at high quality photo stores.

Never use aggressive cleaning liquids such as gasoline, acetone, spirits or nitro cleanser.

Every time the input window is cleaned, there is the possibility of surface damage. Do not clean the input window unless it is absolutely necessary. Be careful and avoid scratches and damage to the input window surface.

Use a cotton swab dipped in pure alcohol or optical cleaning liquid and wipe only on the glass surface. Do not get any cleaning liquid on the metallic parts such as the lens thread, because tiny detached particles may scratch the surface.

Always store the camera with the protective cap or with a lens mounted to avoid dust and dirt on the input window!

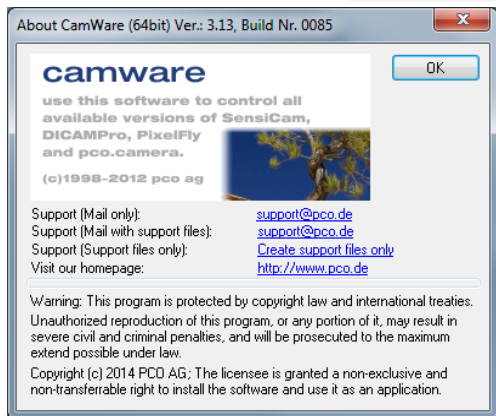
Camera Disposal



The camera includes electronic devices, which can contain materials harmful to the environment. If the camera is to be discarded, please dispose of it in an environmentally responsible manner and use recycling facilities, where available.

A10 CUSTOMER SERVICE AND TROUBLE SHOOTING

If you have a question, which is not adequately addressed in this manual, please contact **PCO** or your **local dealer**.



To speed your request, we need the following information:

- Short description of the problem
- Description of your application
- Camera settings
- Type and version of camera software being used
- Camera serial number
- Operating system (PC)
- Processor type (PC)
- Memory
- Graphic card
- Graphic card setup

Please use the email options under the Help menu (see 7.8)

How to create a logfile:

- Enable log files: **File Menu** ➔ Options ➔ MISC (see 7.3.)
- Reboot your pco.edge
- Repeat the workflow which produces the faults.
- Open the **About CamWare** window (**Menu ? -> About**) and click at the support links to send an email directly to PCO-Support (see 7.8)
- Or visit our website: <http://www.pco.de/support/>

Repair

Before sending the camera for repair, first contact your local dealer or PCO respectively.



When shipping the camera for repair, be certain to carefully pack the camera with proper shipping materials. If possible use the original packaging. Use the protection cap to protect the camera on the lens thread.

Firmware, Software and Driver Update

You will find all necessary software and drivers on the accompanying USB storage device.

For the latest versions please check our website:
<http://www.pco.de/support/supportProducts/scmos-cameras/>

ABOUT PCO



pco.

In 1987, PCO was founded with the objective to develop and to produce specialized, fast and sensitive video camera systems, mainly for scientific applications. Meanwhile the product range of PCO cameras covers digital camera systems with high dynamic range, high resolution, high-speed and low noise, which are sold in the scientific and industrial market all over the world.

Currently PCO is one of the leading manufacturers of scientific cameras. Worldwide representatives, together with our own sales department and technical support assure that we keep in touch with our customers and their needs. The actual wide range of specialized camera systems is the result of technical challenge and product specific know-how. A design according to advanced techniques, a high standard of production and strict quality controls guarantee a reliable operation of the cameras. Our own developments in conjunction with an excellent contact to leading manufacturers of image sensors ensure our access to state-of-the-art CCD- and CMOS-technology for our cameras.

Since 2001, PCO is located in its own facility building in Kelheim at the shore of the beautiful and international river Danube. Here in the county Bavaria, which is well known for its excellent support and conditions for high technology companies, we share the benefits of the simple access to high performance products and services in the surrounding area.

Kelheim itself is a historical town, first documented in 866. The small city is founded at the confluence of the Danube and the Altmühl, which has been converted into the Rhine-Main-Danube bypass channel for water transport. Located in Danube-valley, it is the heart of a beautiful river and forest covered lime plateau landscape. It's landmark, the Hall of Liberation, was built by Ludwig I. in 1863 on the Mount Michael and is visible from all over the city and valley. The beautiful Danube-Gorge, which is protected as natural monument since 1840, is located between Kelheim and the famous abbey Weltenburg.

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